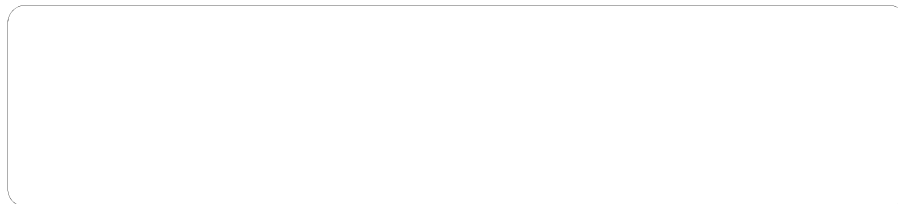


Physical Chemistry III (728342)  
*Chapter 5:* **Molecular Symmetry**

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## Molecular Symmetry

- **Molecular symmetry:**  
The classification of any molecule according to its symmetry, correlating to its molecular properties
- Importance of molecular symmetry



## Group Theory

- The systematic discussion of symmetry is called **Group Theory**.
- The symmetry elements of objects
  - **Symmetry operation:** an action that leaves an object looking the same after it has been carried out
  - **Symmetry element:** an element (plane, line, point) that correlates to the specific symmetry operator (unchanged)

Symmetry Operation	Symmetry Elements
Rotation	Line (axis of rotation)
Reflection	Plane
Inversion	Point

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## Point Group

- **Point Group:** the classification of objects according to symmetry elements corresponding to operations that leave at least one common point unchanged.
- The more extensive classification, including the translation through space, is called **Space Group**.

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## Operations and Symmetry Elements

- Five kinds of symmetry operations in Point Group
  - The identity,  $E$
  - An  $n$ -fold rotation,  $C_n$
  - A reflection,  $\sigma$
  - An inversion,  $i$
  - An  $n$ -fold improper rotation,  $S_n$

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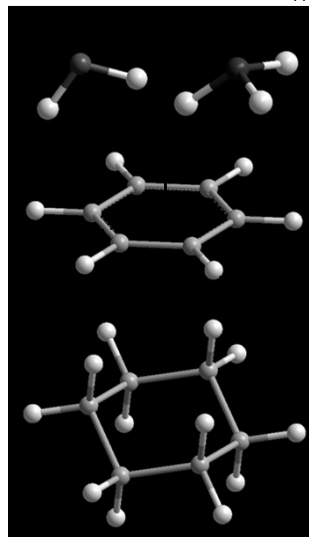
## The Identity, $E$

- The identity operation is doing nothing!
  - Every molecule is indistinguishable from itself thus they have the identity element.

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## An n-fold Rotation, $C_n$

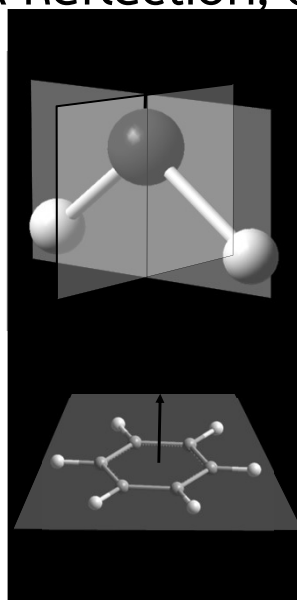
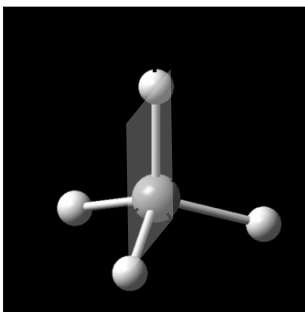
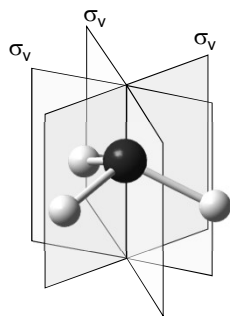
- An n-fold rotation about an n-fold axis of rotation,  $C_n$ , is a rotation through  $360^\circ/n$ 
  - $C_1 = E$
  - $C_2 = 180^\circ$  rotation
  - $C_3 = 120^\circ$  rotation ( $C_3'$  and  $C_3''$ )
  - $C_6 = 60^\circ$  rotation ( $C_1^1, C_1^2 \dots C_1^5$ )
- If a molecule possesses several rotational axes, the one with the greatest value of n is called **the principal axis (Z)**.



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## A Reflection, $\sigma$

- A reflection is a mirror plane.
  - $\sigma_v$  – parallel to the principle axis
  - $\sigma_d$  – parallel to the principle axis and bisect the angle between two  $C_2$  axes
  - $\sigma_h$  – perpendicular to the principle axis

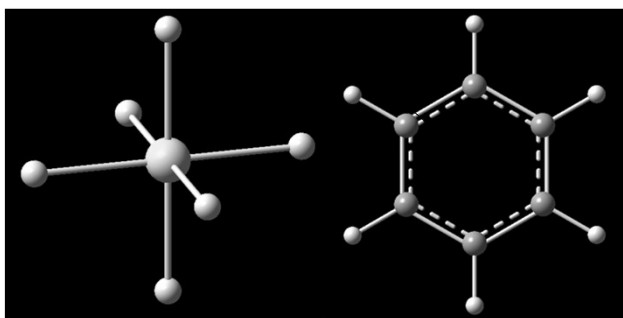
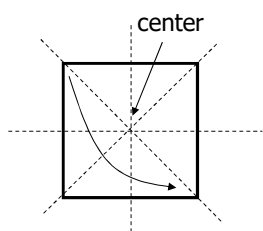


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## An Inversion, $i$

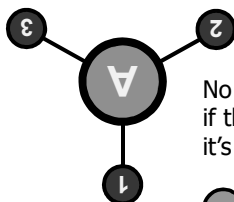
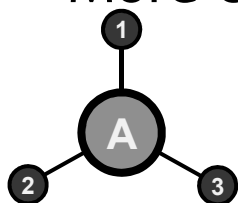
- An inversion through a center of symmetry
  - If the origin point is the center of symmetry

$$\hat{i}(x, y, z) = (-x, -y, -z)$$

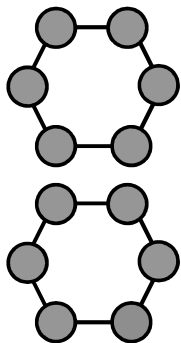


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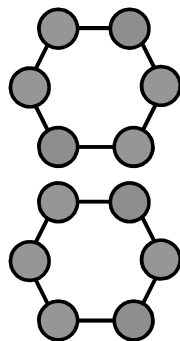
## More examples about inversion



No inversion  
if the inversion point is on atom A,  
it's changed upon the inversion



the inversion point is  
at the center



the inversion point is  
at the center

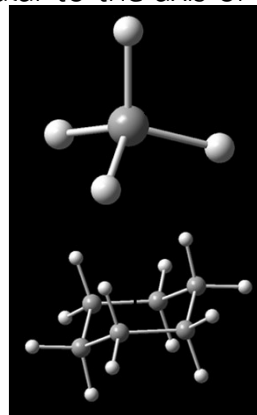
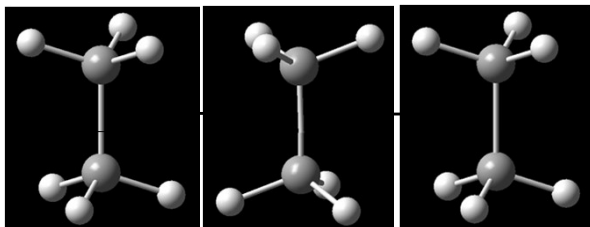
No inversion

No inversion

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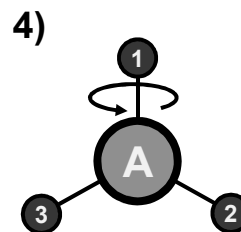
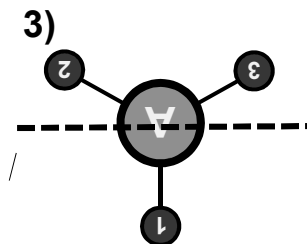
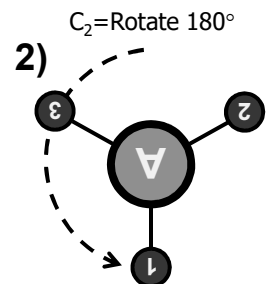
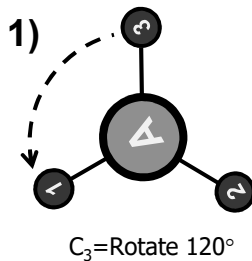
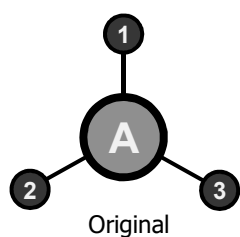
## An n-fold Improper Rotation, $S_n$

- An n-fold improper rotation is composed of two successive transformation:
  - Rotation through  $360^\circ/n$
  - Reflection through a plane perpendicular to the axis of that rotation.



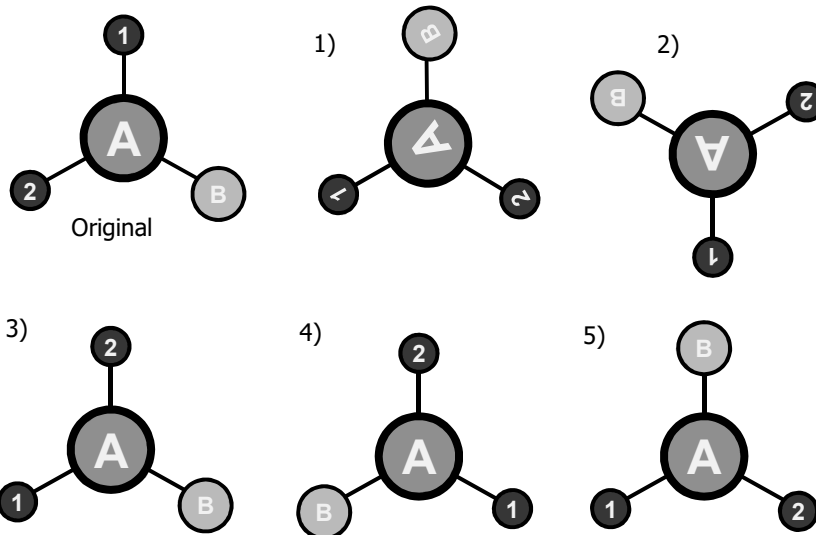
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## Example of Acceptable Operator



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## What operator is applied?



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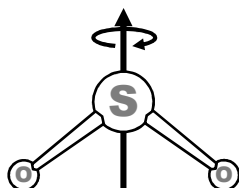
## The Symmetry Classification of Molecules

- Molecules with the same list of elements are classified to the same group.
  - The groups  $C_1$ ,  $C_i$  and  $C_s$  (no rotational axis)
  - The groups  $C_n$ ,  $C_{nv}$  and  $C_{nh}$  (n-fold axis)
  - The groups  $D_n$ ,  $D_{nh}$ ,  $D_{nd}$  (n-fold axis and n perpendicular  $C_2$ s)
  - The groups  $S_n$  (n-fold improper axis)
  - The cubic groups
    - ♦ Tetrahedral groups ( $T$ ,  $T_d$ ,  $T_h$ )
    - ♦ Octahedral groups ( $O$ ,  $O_h$ )
    - ♦ Icosahedral groups ( $I$ )

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## Example of Character Table

- The characters of all representations are tabulated in a character table.

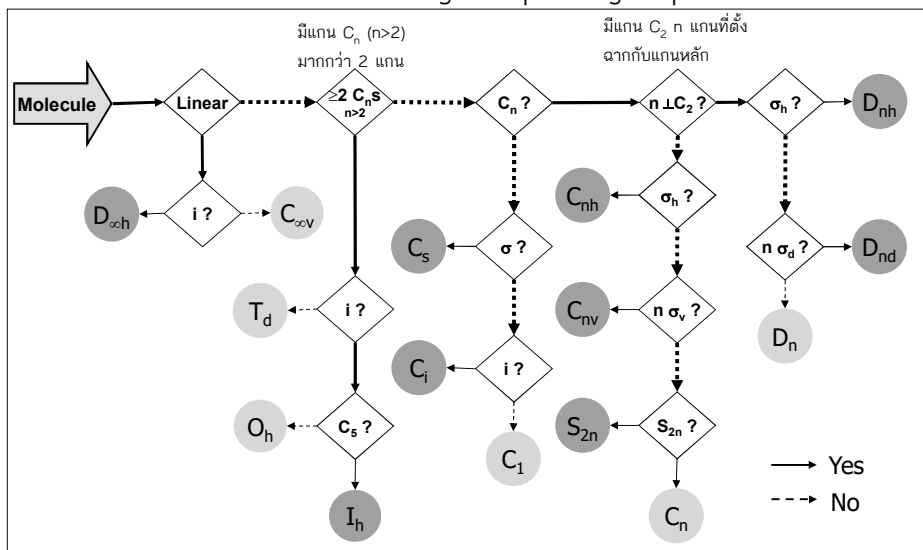


$C_{2v}$	E	$C_2$	$\sigma_v$	$\sigma_v'$	$h=4$	
$A_1$	1	1	1	1	Z	$z^2, y^2, x^2$
$A_2$	1	1	-1	-1		xy
$B_1$	1	-1	1	-1	X	xz
$B_2$	1	-1	-1	1	y	yx

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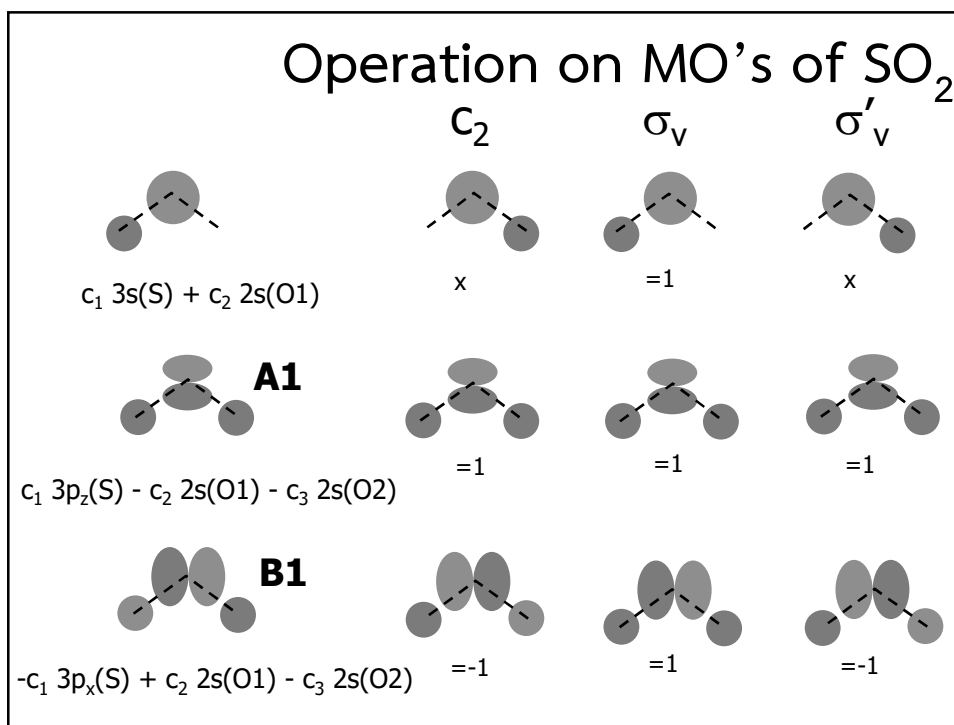
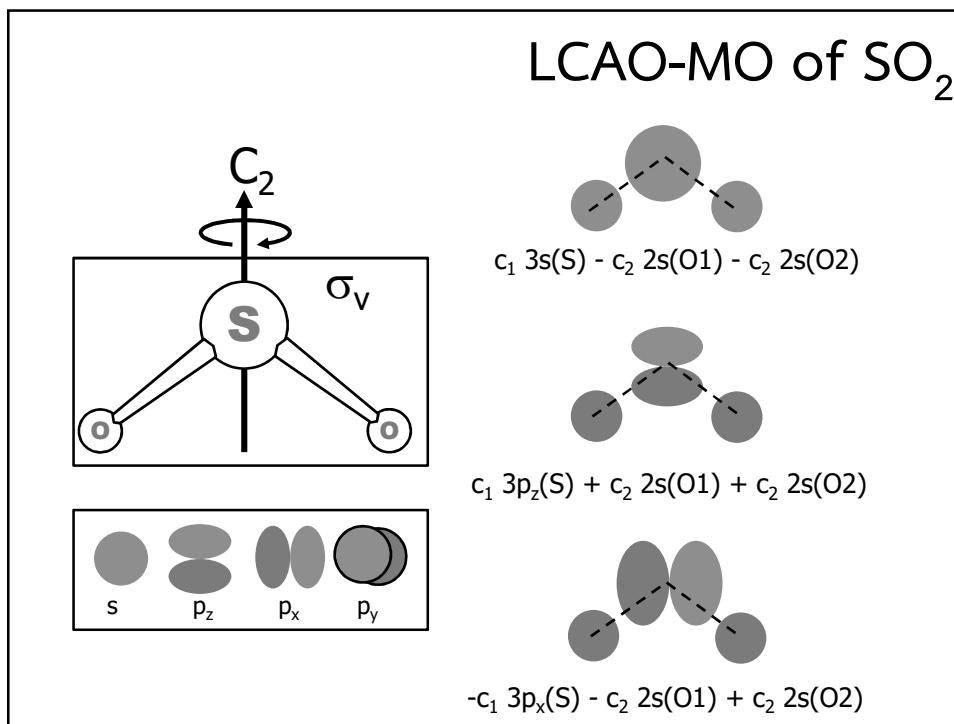
## Determining the Point Group

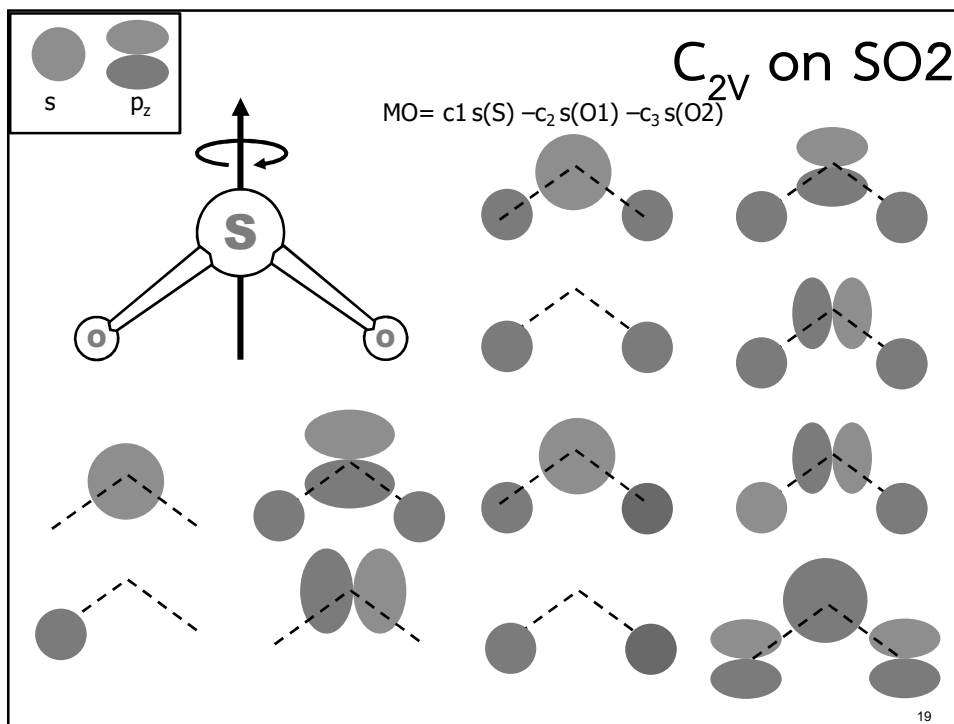
- A flowchart for determining the point group of a molecule



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## Character Table

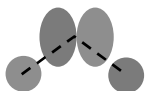
- **Character Table** is a table that characterizes the different symmetry types possible in the point group.
- The entries in a complete character table are derived by using the formal techniques of group theory.

<b>C<sub>2v</sub></b>	<b>E</b>	<b>C<sub>2</sub></b>	<b>σ<sub>v</sub></b>	<b>σ<sub>v</sub>'</b>	<b>h=4</b>	
<b>A<sub>1</sub></b>	1	1	1	1	Z	$z^2, y^2, x^2$
<b>A<sub>2</sub></b>	1	1	-1	-1		xy
<b>B<sub>1</sub></b>	1	-1	1	-1	X	xz
<b>B<sub>2</sub></b>	1	-1	-1	1	y	yx

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## Operation & Matrix

$$-c_1 3p_x(S) + c_2 2s(O1) - c_3 2s(O2)$$



**B1**

$$\hat{C}_2(3p_s, 2s_{O1}, 2s_{O2}) = (3p_s, 2s_{O1}, 2s_{O2}) \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix} = (-3p_s, -2s_{O2}, -2s_{O1})$$

$$\hat{\sigma}_v(3p_s, 2s_{O1}, 2s_{O2}) = (3p_s, 2s_{O1}, 2s_{O2}) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = (3p_s, 2s_{O1}, 2s_{O2})$$

$$\hat{\sigma}'_v(3p_s, 2s_{O1}, 2s_{O2}) = (3p_s, 2s_{O1}, 2s_{O2}) \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix} = (-3p_s, -2s_{O2}, -2s_{O1})$$

## Representations and Characters

- All the operators can be written in the matrix form.
- The matrix is called a representation of an operator.

•  $C_{2v}$

$$\mathbf{D}(E) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{D}(\sigma_v) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{D}(C_2) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\mathbf{D}(\sigma'_v) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

- The Matrix representative is called  $\Gamma^{(n)}$ , where n is the dimension of the matrix
- The character of the representation matrix is the sum of diagonal elements.

$$\Gamma(E) = 3 \quad \Gamma(\sigma_v) = 3 \quad \Gamma(C_2) = -1 \quad \Gamma(\sigma'_v) = -1$$

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## Reduce- and Irreducible Representation

- Inspection of the representatives reveals that they are all of block-diagonal form.
- This shows that the  $p_s$  is never mixed with the rest.

$$\mathbf{D}(E) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \boxed{1} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \mathbf{D}(\sigma_v) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \boxed{1} & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \mathbf{D}(C_2) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & \boxed{0} & -1 \\ 0 & -1 & 0 \end{bmatrix} \quad \mathbf{D}(\sigma'_v) = \begin{bmatrix} -1 & 0 & 0 \\ 0 & \boxed{0} & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

- The 3-D representative matrix ( $\Gamma^{(3)}$ ) can be separated into  $\Gamma^{(1)} + \Gamma^{(2)}$

$$\Gamma^{(1)} \Rightarrow \mathbf{D}(E)=1 \quad \mathbf{D}(\sigma_v)=1 \quad \mathbf{D}(C_2)=1 \quad \mathbf{D}(\sigma'_v)=-1$$

$$\Gamma^{(2)} \Rightarrow \mathbf{D}(E) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathbf{D}(\sigma_v) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \mathbf{D}(C_2) = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \quad \mathbf{D}(\sigma'_v) = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

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- According to the matrix representation,  $2s(O1)$  and  $2s(O2)$  are mixed together.
- Using the LC, we can write the new basis as  $s_A = 2s(O1) + 2s(O2)$  and  $s_B = 2s(O1) - 2s(O2)$



$$\Gamma^{(1)} \Rightarrow \mathbf{D}(E)=1 \quad \mathbf{D}(\sigma_v)=1 \quad \mathbf{D}(C_2)=1 \quad \mathbf{D}(\sigma'_v)=1$$



$$\Gamma^{(1)} \Rightarrow \mathbf{D}(E)=1 \quad \mathbf{D}(\sigma_v)=1 \quad \mathbf{D}(C_2)=-1 \quad \mathbf{D}(\sigma'_v)=-1$$

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## The Structure of Character Tables

Group	Symmetry Operations Class			Order (# operations)	
$C_{3v}$	$E$	$2C_3$	$3\sigma_v$	$h=6$	
$A_1$	1	1	1	Z	$z^2, x^2 + y^2$
$A_2$	1	1	-1		
$E$	2	-1	0	(x,y)	$(xy, x^2-y^2), (xz, yz)$

Irreducible Representations

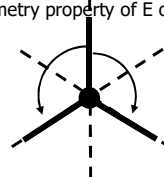
Symmetry Properties ( $\chi$ )

# of degeneracy of each representative is specified by the symmetry property of E operation or  $\chi(E)$ .

Labels A, B: 1-D E: 2-D T: 3-D

$A \rightarrow \chi(C_n) = 1$   $B \rightarrow \chi(C_n) = -1$

$1 \rightarrow \chi(\sigma_v) = 1$   $2 \rightarrow \chi(\sigma_v) = -1$



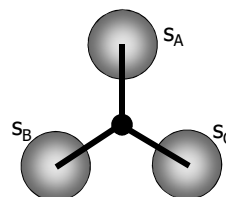
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## The Classification of LC of Orbitals

### ■ $NH_3$

- LCAO:  $\psi_1 = \psi_A + \psi_B + \psi_C$

$$\chi(E) = 1 \quad \chi(C_3) = 1 \quad \chi(\sigma_v) = 1$$

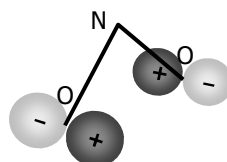


this orbital is of symmetry species  $A_1$  and it contributes to  $a_1$  MO in  $NH_3$ .

### ■ $NO_2$

$$\psi_1 = \psi_A - \psi_B$$

- LCAO:  $\chi(E) = ?$   $\chi(C_2) = ?$   $\chi(\sigma_v) = ?$   $\chi(\sigma'_v) = ?$



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## Orbitals with nonzero overlap

- Only orbitals of the same symmetry species may have nonzero overlap, so only orbitals of the same symmetry species form bonding and antibonding combinations.

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## Vanishing Integrals & Orbital Overlap

- The value of integrals and orbital overlap is independent of the orientation of the molecule.

$$I = \int f_1 f_2 d\tau$$

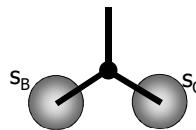
- $I$  is invariant under any symmetry operation of the molecule, otherwise it must be zero.
- For  $I$  not to be zero, the integrand  $f_1 f_2$  must have symmetry species  $A_1$ .

- Example:  $f_1 = s_B$  and  $f_2 = s_C$  of  $\text{NH}_3$

$$f_1: \quad 1 \quad 1 \quad 1$$

$$f_2: \quad 2 \quad -1 \quad 1$$

$$f_1 f_2: \quad 2 \quad -1 \quad 1 \rightarrow \text{not } A_1 \quad I = \int s_B s_C d\tau = 0$$



- Problem:  $f_1 = s_N$  and  $f_2 = s_A + s_B + s_C$  of  $\text{NH}_3$

$$I = \int f_1 f_2 d\tau = 0 \quad ?$$

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## Vanishing Integrals and Selection Rules

- Integrals of the form  $I = \int f_1 f_2 f_3 d\tau$  are common in quantum mechanics.
- For the integral to be nonzero, the product  $f_1 f_2 f$  must span  $A_1$  or contain a component that span  $A_1$ .
- The intensity of line spectra arises from a molecular transition between some initial state  $i$  and a final state  $f$  and depends on the electric transition dipole moment  $\mu_{fi}$ .

$$\mu_{z,fi} = -e \int \psi_f^* z \psi_i d\tau = \langle f | \mu_z | i \rangle$$

$C_{2v}$	<b>E</b>	<b>C<sub>2</sub></b>	<b><math>\sigma_v</math></b>	<b><math>\sigma_v'</math></b>
<b>B<sub>1</sub></b>	1	-1	1	-1
<b>z</b>	1	1	1	1
<b>A<sub>1</sub></b>	1	1	1	1
<b>A<sub>1</sub>zB<sub>1</sub></b>	1	-1	1	1

$C_{2v}$	<b>E</b>	<b>C<sub>2</sub></b>	<b><math>\sigma_v(xz)</math></b>	<b><math>\sigma_v(yz)</math></b>	
<b>A<sub>1</sub></b>	1	1	1	1	$z, x^2, y^2, z^2$
<b>A<sub>2</sub></b>	1	1	-1	-1	$R_z, xy$
<b>B<sub>1</sub></b>	1	-1	1	-1	$x, R_y, xz$
<b>B<sub>2</sub></b>	1	-1	-1	1	$y, R_x, yz$

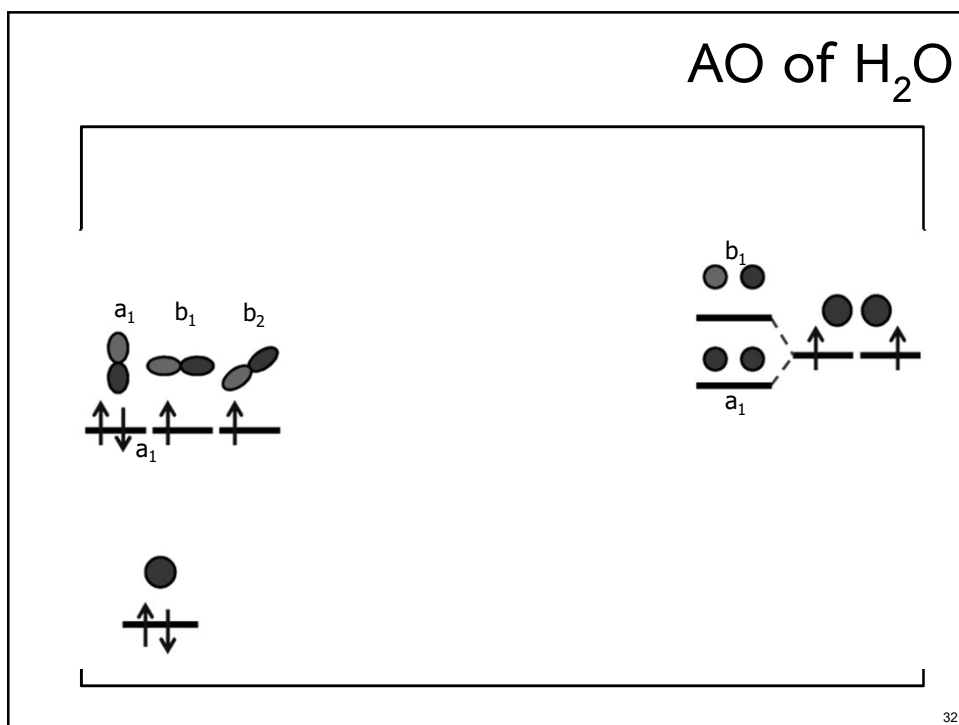
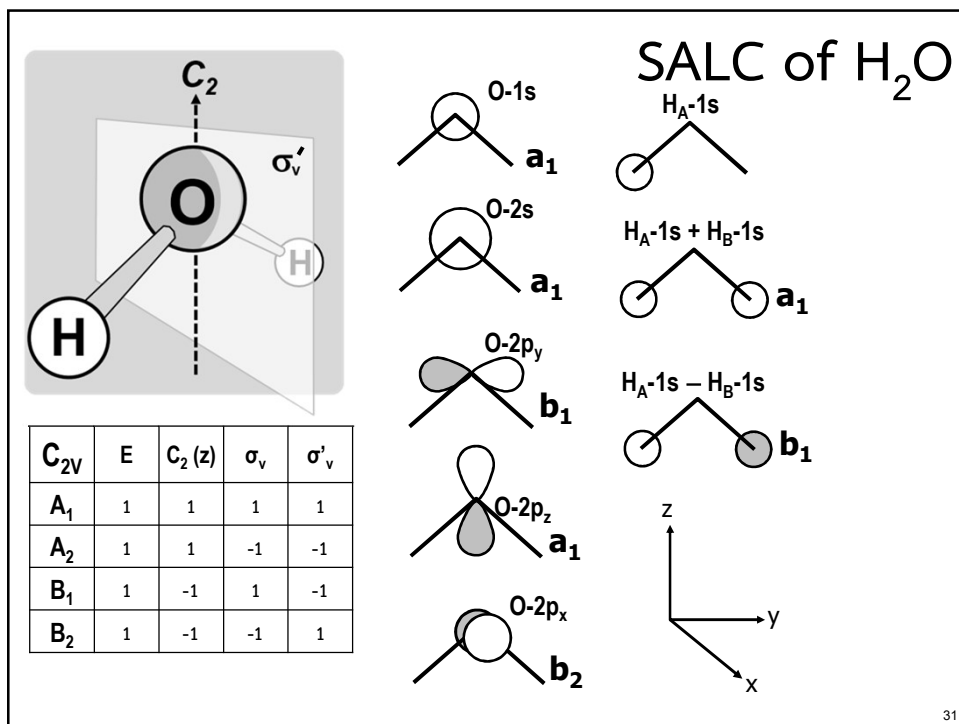
→  $\mu_{z,fi} = 0$  if  $fzi$  does not span species  $A_1$

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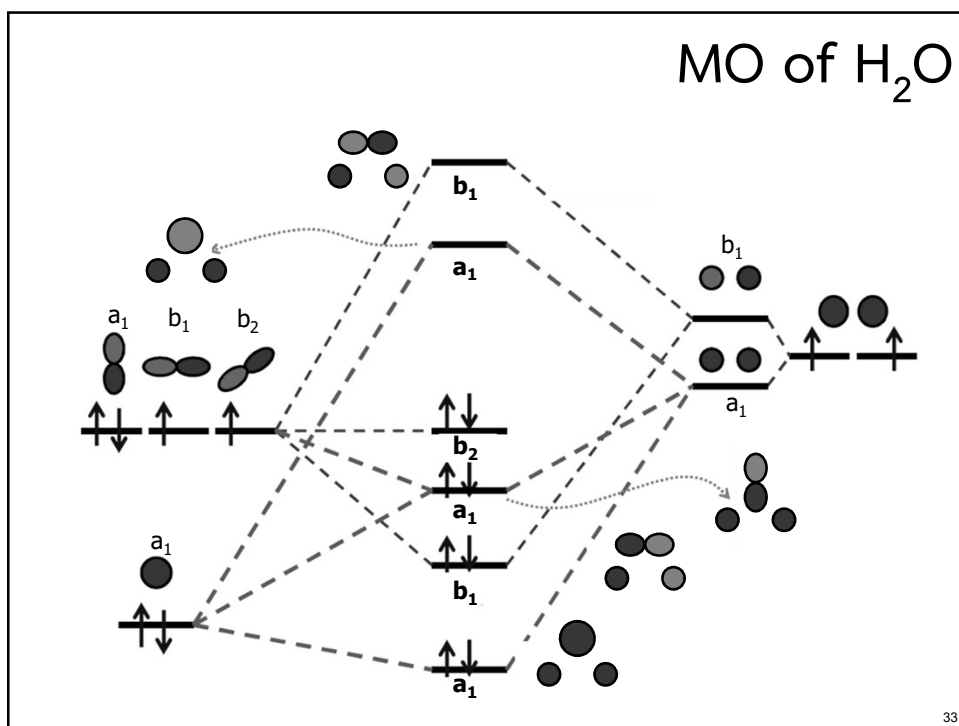
- In many cases, the product of functions  $f_1$  and  $f_2$  spans a sum of irreducible representations.
- In these cases, we have to decompose the reducible representation into irreducible representations

$C_{2v}$	<b>E</b>	<b>C<sub>2</sub></b>	<b><math>\sigma_v</math></b>	<b><math>\sigma_v'</math></b>
<b>A<sub>2</sub></b>	1	1	-1	-1
<b>B<sub>1</sub></b>	1	-1	1	-1
<b>A<sub>2</sub>+B<sub>1</sub></b>	2	0	0	-2

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## Symmetry-adapted Linear Combinations

- Symmetry-adapted linear combination (SALC) are the building blocks of LCAO-MO
- To construct the SALC from basis:
  1. Construct a table showing the effect of each operation on each orbital of the original basis.
  2. To generate the combination of a specified symmetry species, take each column in turn and:
    - a) Multiply each member of the column by the character of the corresponding operation.
    - b) Add together all the orbitals in each column with the factors as determined in a).
    - c) Divide the sum by the order of the group.

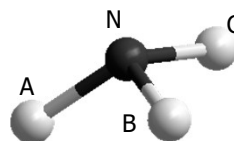
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## Example of building SALC

- s-orbitals of  $\text{NH}_3$ 
  - Original basis are  $s_N, s_A, s_B, s_C$

NH <sub>3</sub>	Original basis			
	s <sub>N</sub>	s <sub>A</sub>	s <sub>B</sub>	s <sub>C</sub>
E	s <sub>N</sub>	s <sub>A</sub>	s <sub>B</sub>	s <sub>C</sub>
C <sub>3</sub> <sup>+</sup>	s <sub>N</sub>	s <sub>B</sub>	s <sub>C</sub>	s <sub>A</sub>
C <sub>3</sub> <sup>-</sup>	s <sub>N</sub>	s <sub>C</sub>	s <sub>A</sub>	s <sub>B</sub>
σ <sub>v</sub>	s <sub>N</sub>	s <sub>A</sub>	s <sub>C</sub>	s <sub>B</sub>
σ <sub>v</sub> '	s <sub>N</sub>	s <sub>B</sub>	s <sub>A</sub>	s <sub>C</sub>
σ <sub>v</sub> "	s <sub>N</sub>	s <sub>C</sub>	s <sub>B</sub>	s <sub>A</sub>

C <sub>3v</sub>	E	2C <sub>3</sub>	3σ <sub>v</sub>
A <sub>1</sub>	1	1	1
A <sub>2</sub>	1	1	-1
E	2	-1	0



For A<sub>1</sub> combination (1,1,1,1,1)

$$\psi_1 = \frac{1}{6}(s_N + s_N + \dots s_N) = s_N$$

$$\psi_2 = \psi_3 = \psi_4 = \frac{1}{6}(s_A + s_B + s_C + s_A + s_B + s_C) = \frac{1}{3}(s_A + s_B + s_C)$$

$$\Psi = c_1\psi_1 + c_2\psi_2 + c_3\psi_3 + c_4\psi_4 = c_N s_N + c_H s_H$$

$$\text{when } s_H = (s_A + s_B + s_C)$$

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