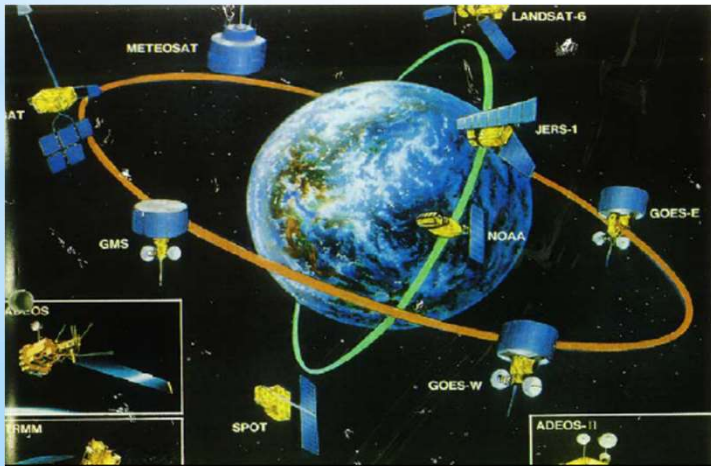


Introduction to Remote sensing and applications



รศ.ดร.วีระเกษตร สนวนพกา
D.Eng(RS&GIS)

*Contents

*Concept of Remote Sensing

*Overview of Remote Sensing
Technology

*Application of Remote
Sensing

*What is Remote Sensing ?

“Remote Sensing is defined as the science and technology by which *characteristics* of objects of interest can be *identified* without direct contact”

*Type of remote sensing

*Optical remote sensing

- * High resolution (Quick bird, IKONOS, LANDSAT, SPOT, THEOS (Thailand Earth Observation System))

- * Moderate or Low resolution (Terra-MODIS,NOAA)

*Non Optical remote sensing (Microwave)

- Passive Sensor

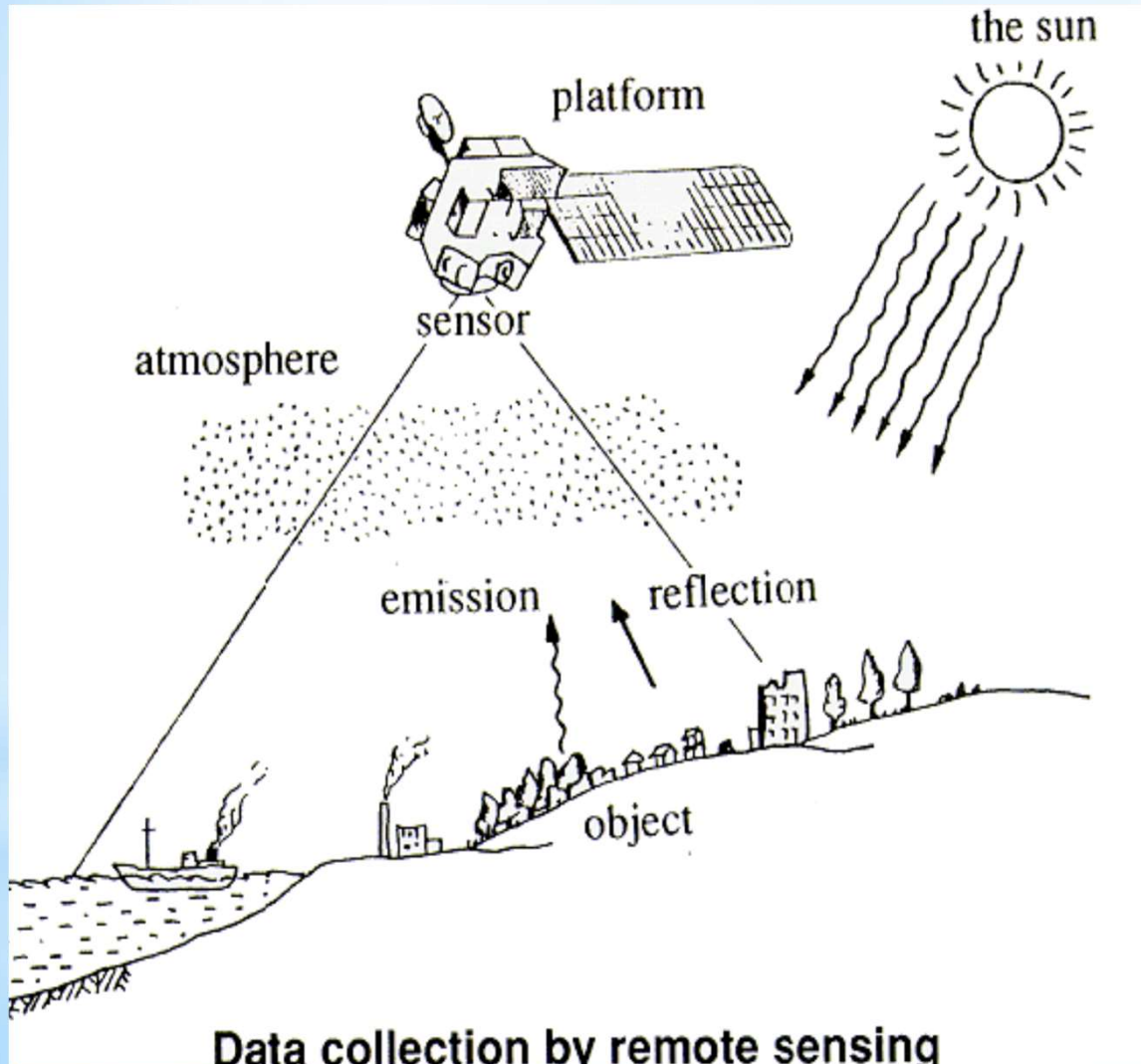
- Active Sensor

- * Synthetic Aperture Radar (SAR)

- * Real Aperture Radar (RAR)

- * Synthetic Aperture Radar Interferometry (InSAR)

* Remote Sensing System



Satellite Remote Sensing - Earth Observation Broad Area

**Quick,
180 kmx180km
30 sec
Repetitive**

Data collection by remote sensing

* Architecture of orbital system

* Low earth orbit (LEO)

→ $T < 25$ min , $h < 6,000$ km

→ Earth sensing, some communication Human space flight

* Medium earth orbit (MEO)

→ 225 min $< T < 24$ hr. $6,000$ km $< h < 36,000$ km

→ some earth sensing, navigation (military)

* Geo-stationary orbit (GEO)

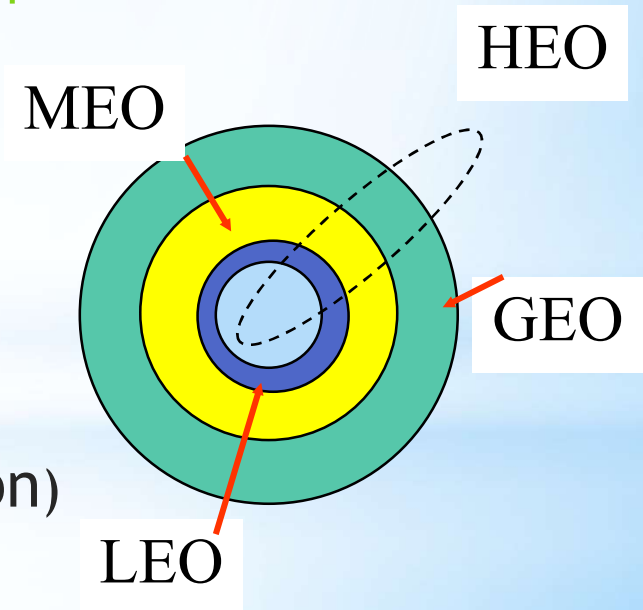
→ $T = 24$ hr, $h = 36,000$ km

→ geosynchronous, geostationary

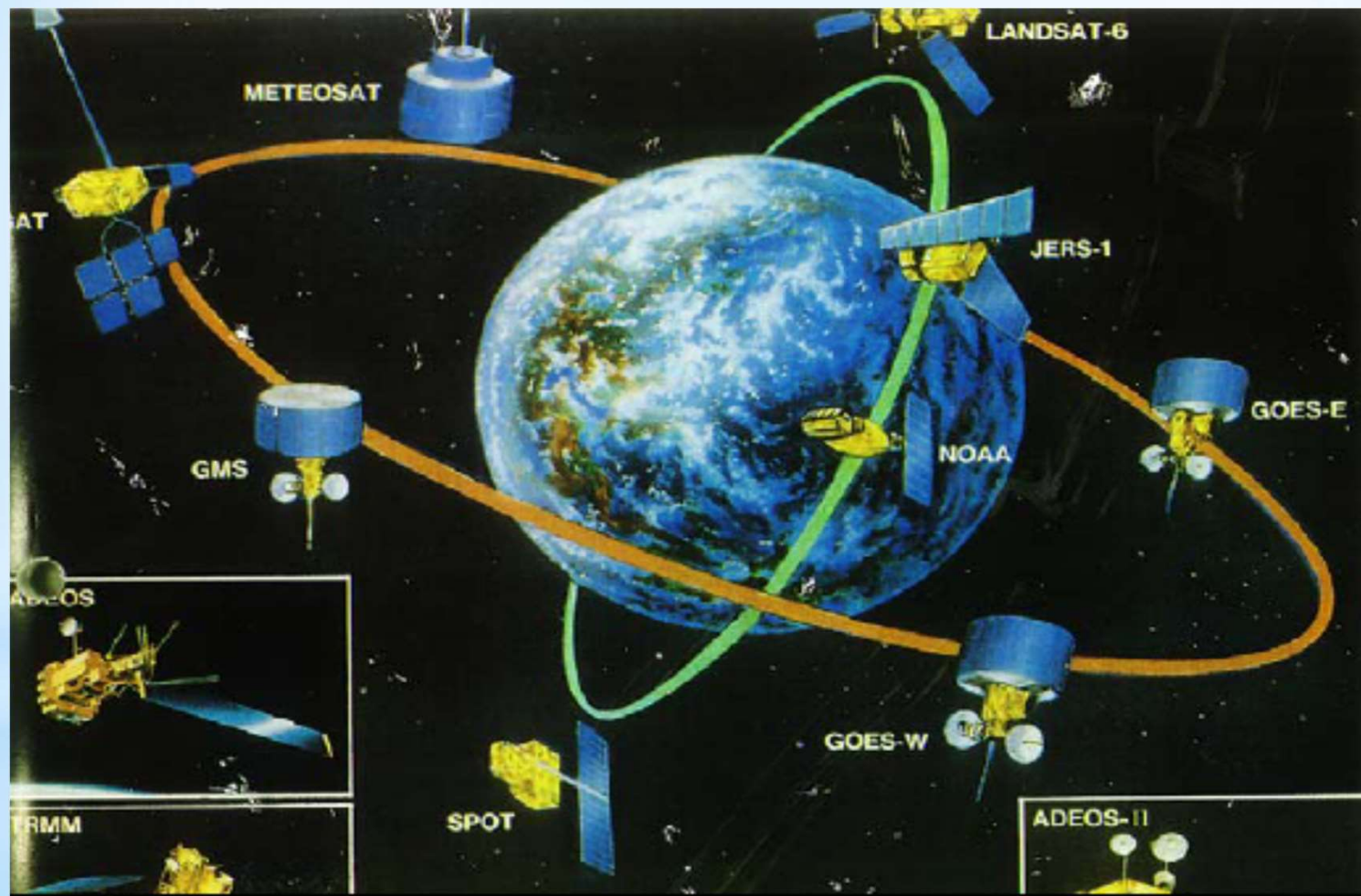
* Higher Earth orbit (HEO)

→ $T > 24$ hr, $h > 36,000$ km

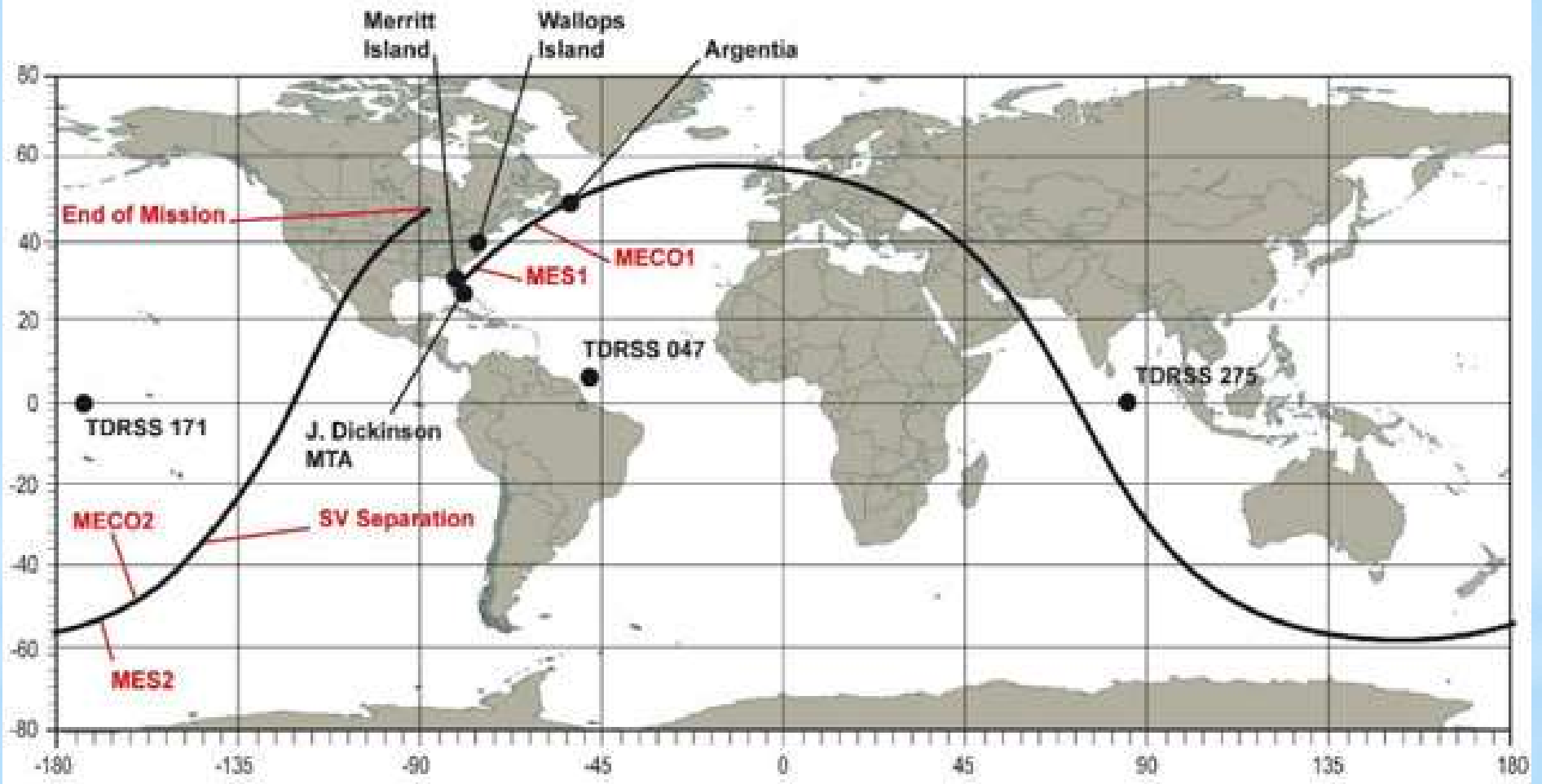
→ moninya orbit(military,comunication)



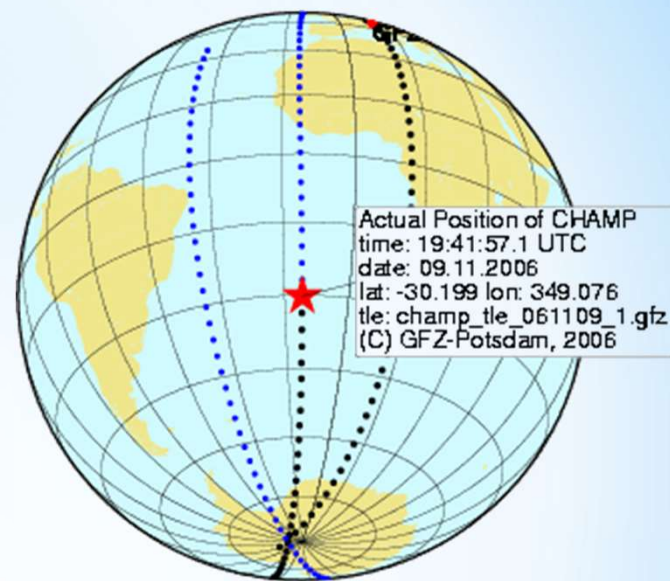
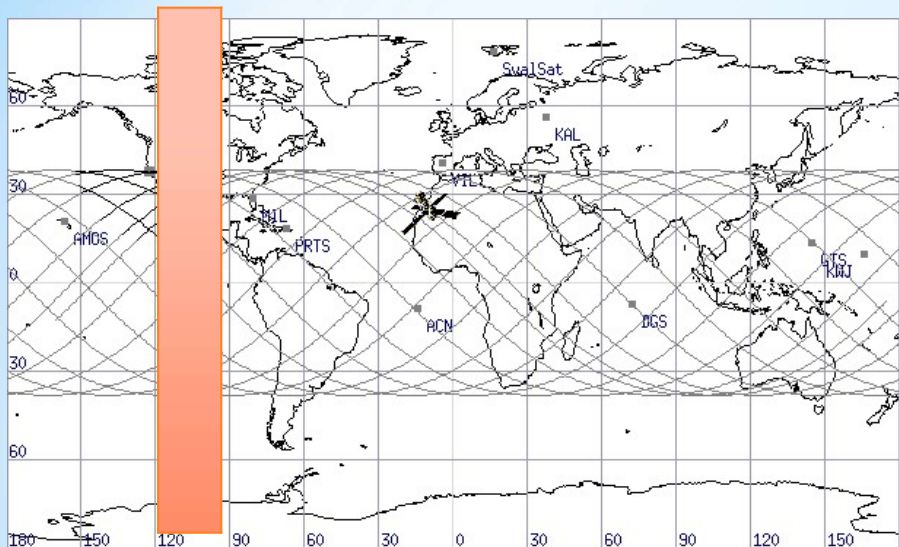
* Polar Orbit Satellite and Geostationary Satellite



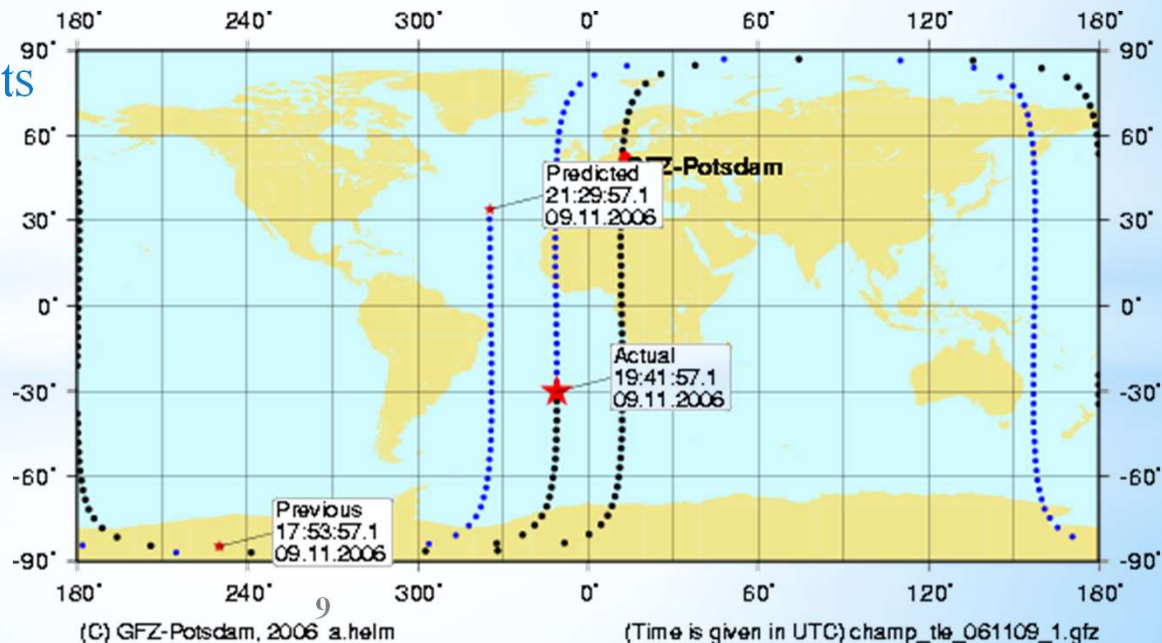
*Ground track



How high you can go? [h site](#)



Ground Track for 16 Orbits

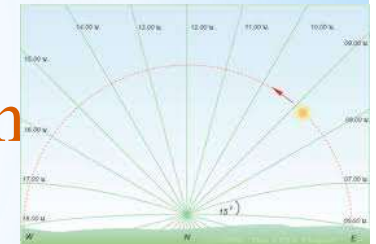
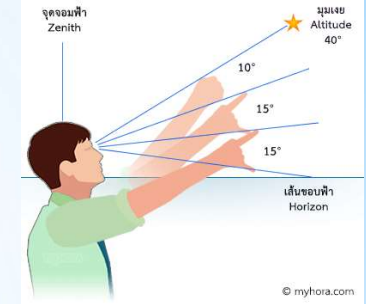
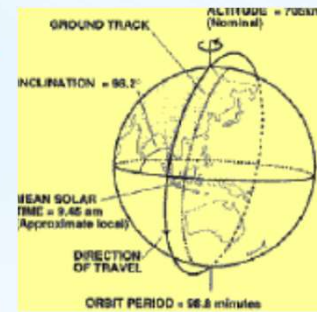


(C) GFZ-Potsdam, 2006 a.helm

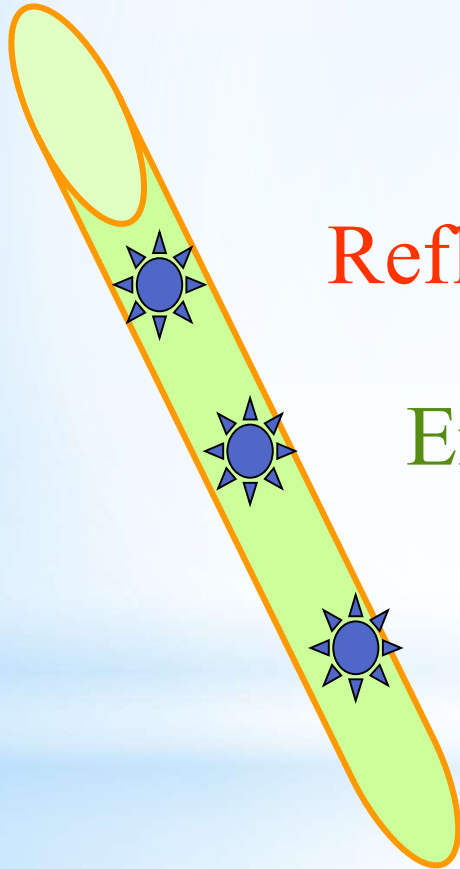
(Time is given in UTC) champ_tle_061109_1.gfz

*Several Important Numbers

- Radius of Earth approx. 6,300km
(a=6377, b=6356, Bessel)
- Altitude of Polar Orbit Satellite •300km - 900km
- Landsat 705km, JERS-1 568km, SPOT 822km, NOAA 833-870km
- Altitude of Geo-stationary Satellite 35,800km
- Speed of light 300,000km/sec
- Speed of Satellite (relative to the earth)
- 6.5km/sec = 23,400km/hour,
Jet Passenger Aircraft 900km/h



*What Does a Sensor Measure?

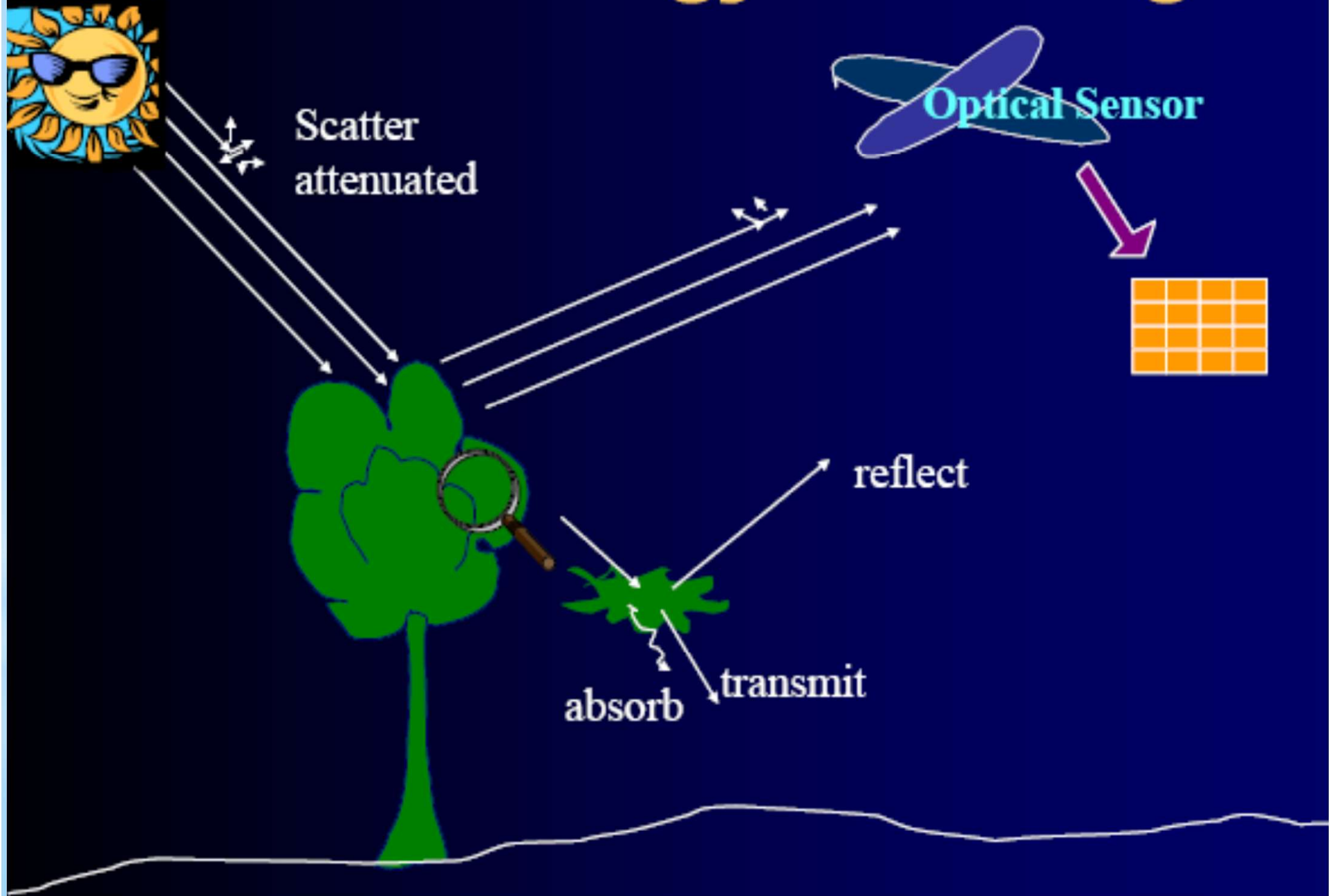


Reflected energy from the Earth

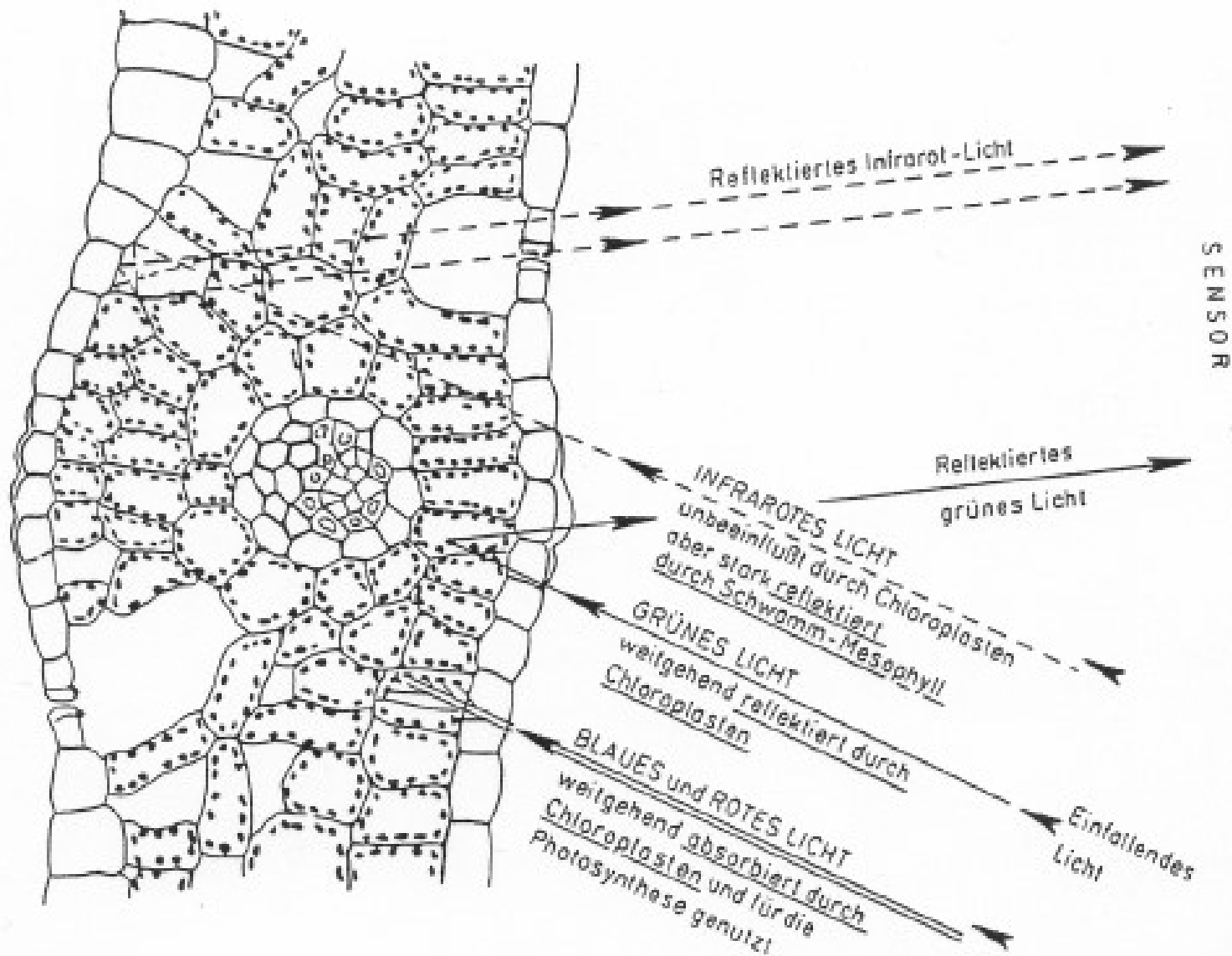
Emitted energy from the Earth

Scattered Energy from the Earth

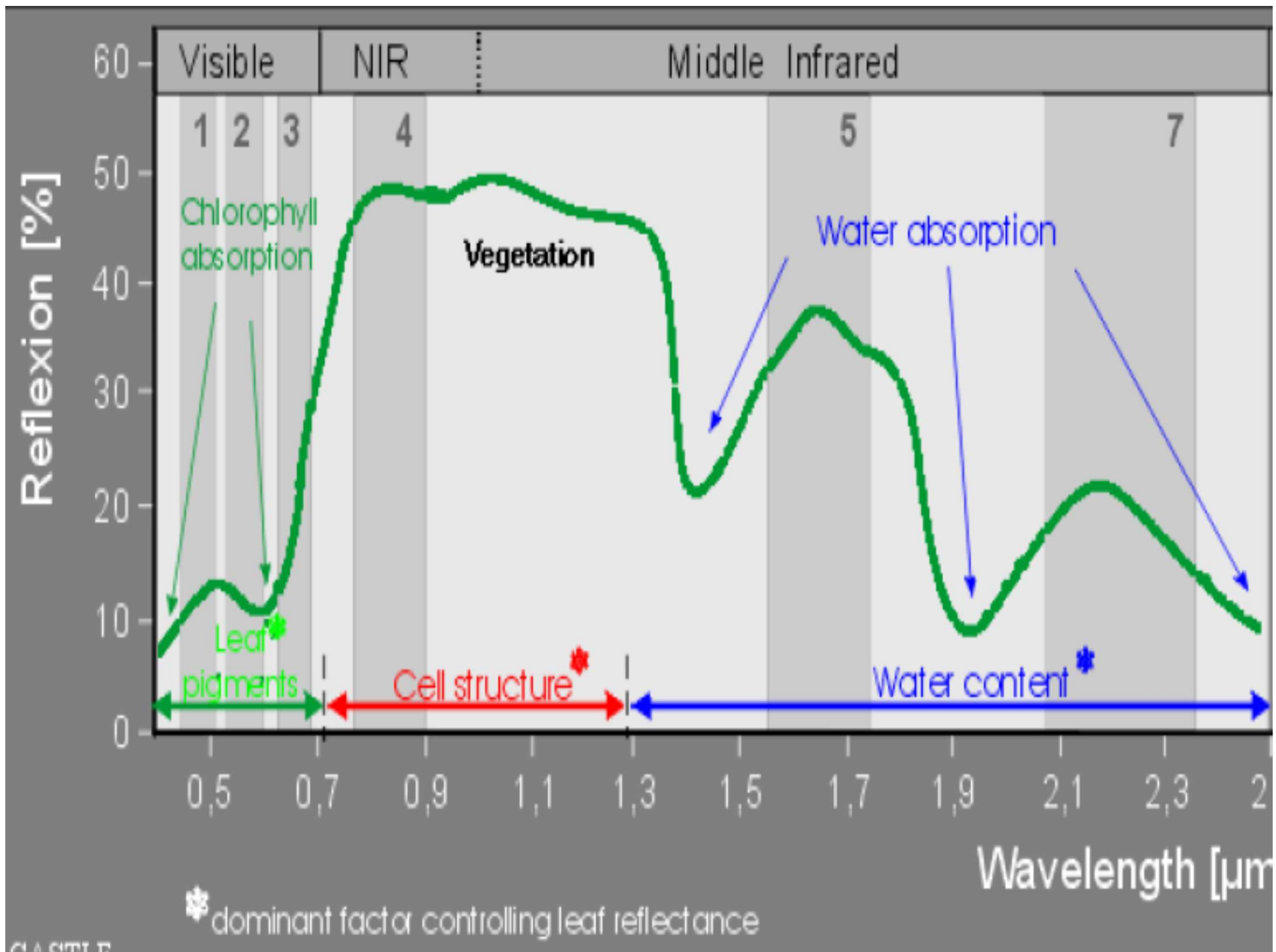
Reflected Energy of Sun Light



Reflexionseigenschaften von Vegetation







*Type of remote sensing

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* Optical Remote sensing



Landsat 7 ETM+ Image around Lake Titicaca, Bolivia/Peru

QuickBird Imagery of Suvarnabhumi Airport and Vicinity
acquired on November 21, 2005

Bangkok-Chon Buri New Highway

On Nut Rd.

Lad Krabang Rd.

King Kaew Rd.

Bang Na-Trad
Highway

© DigitalGlobe/GISTDA_2005



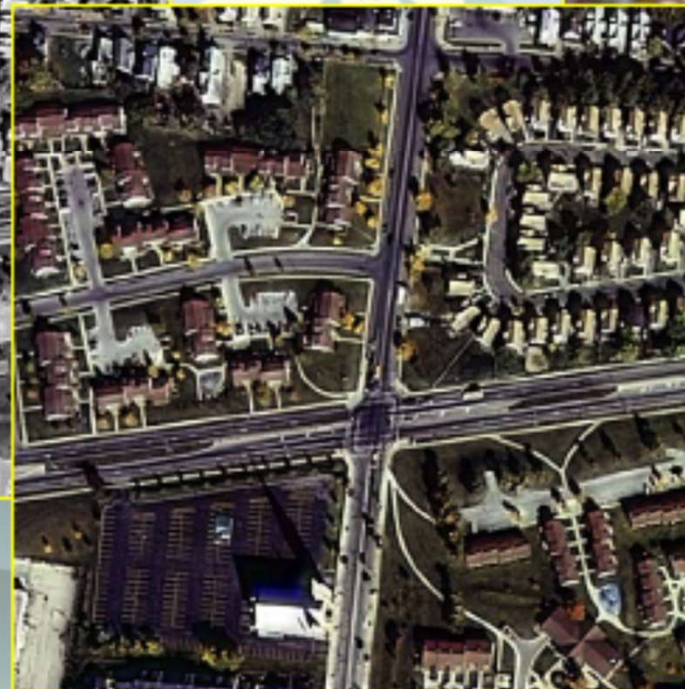
Pan-sharpened imagery – Ikonos example



**1-Meter
Panchromatic Image**



**4-Meter Multispectral
Image**



1-Meter Pan-Sharpended Image

* Microwave-RS (Non optical)

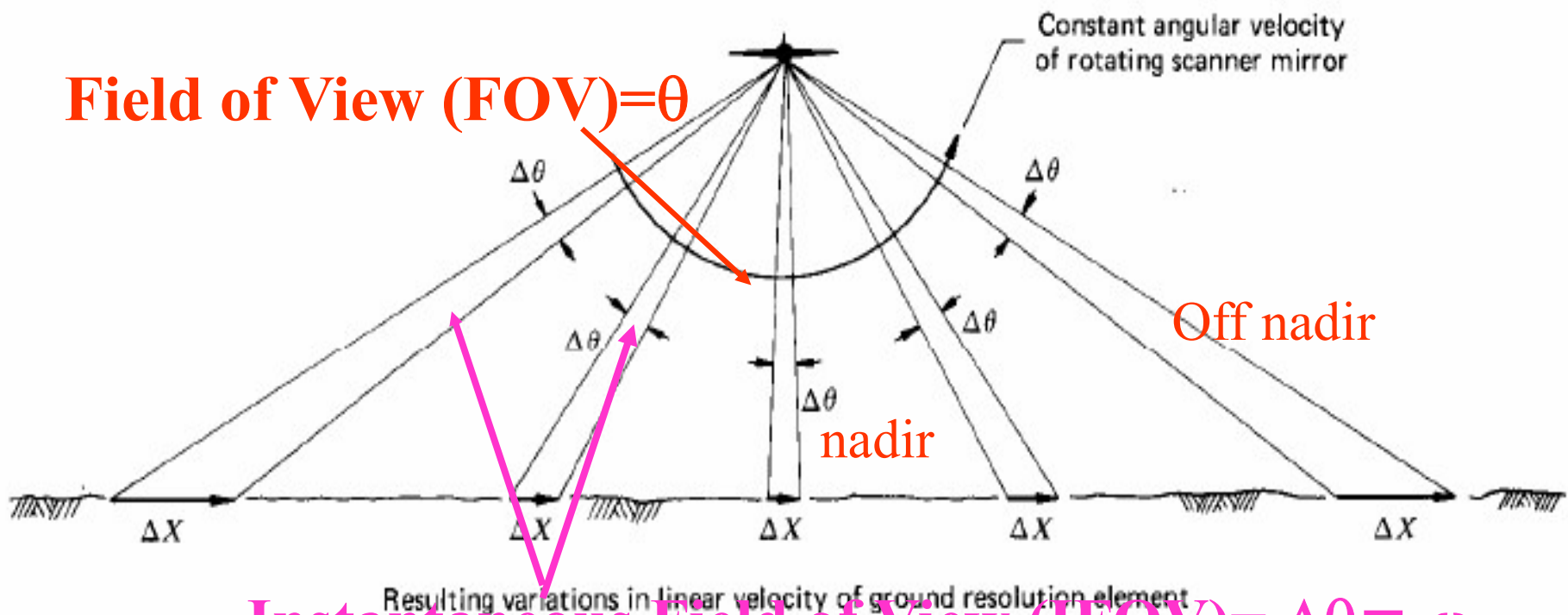


JERS1-OPS
(Optical sensor)

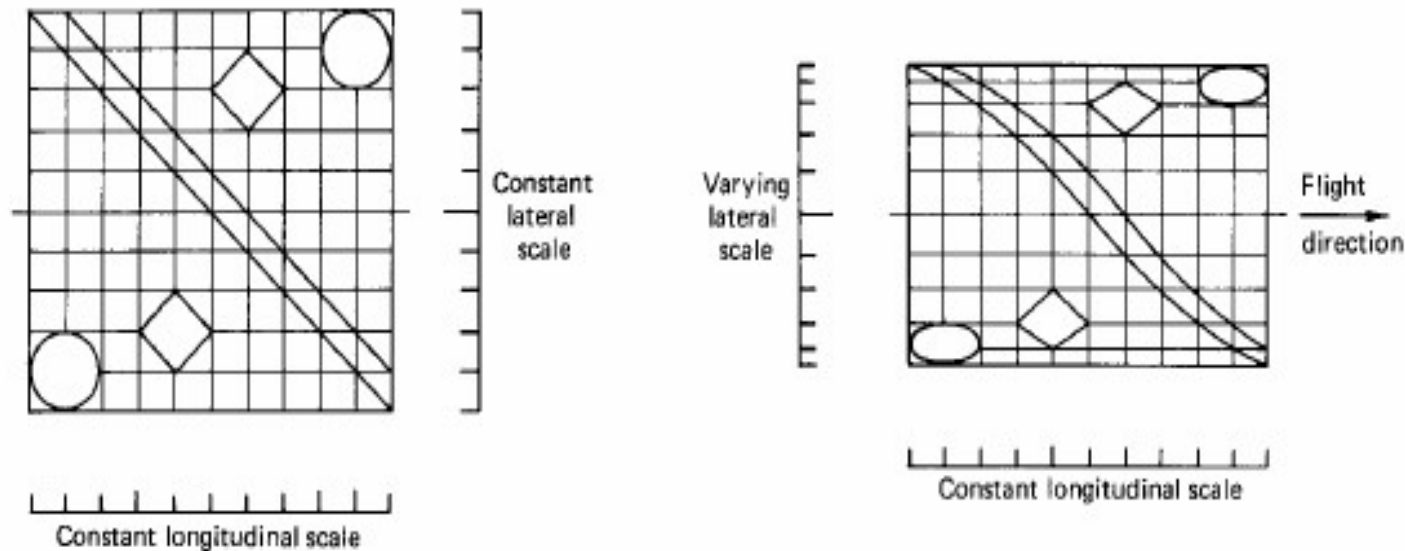


JERS1-sar
(active microwave sensor)

Field of View (FOV) = θ

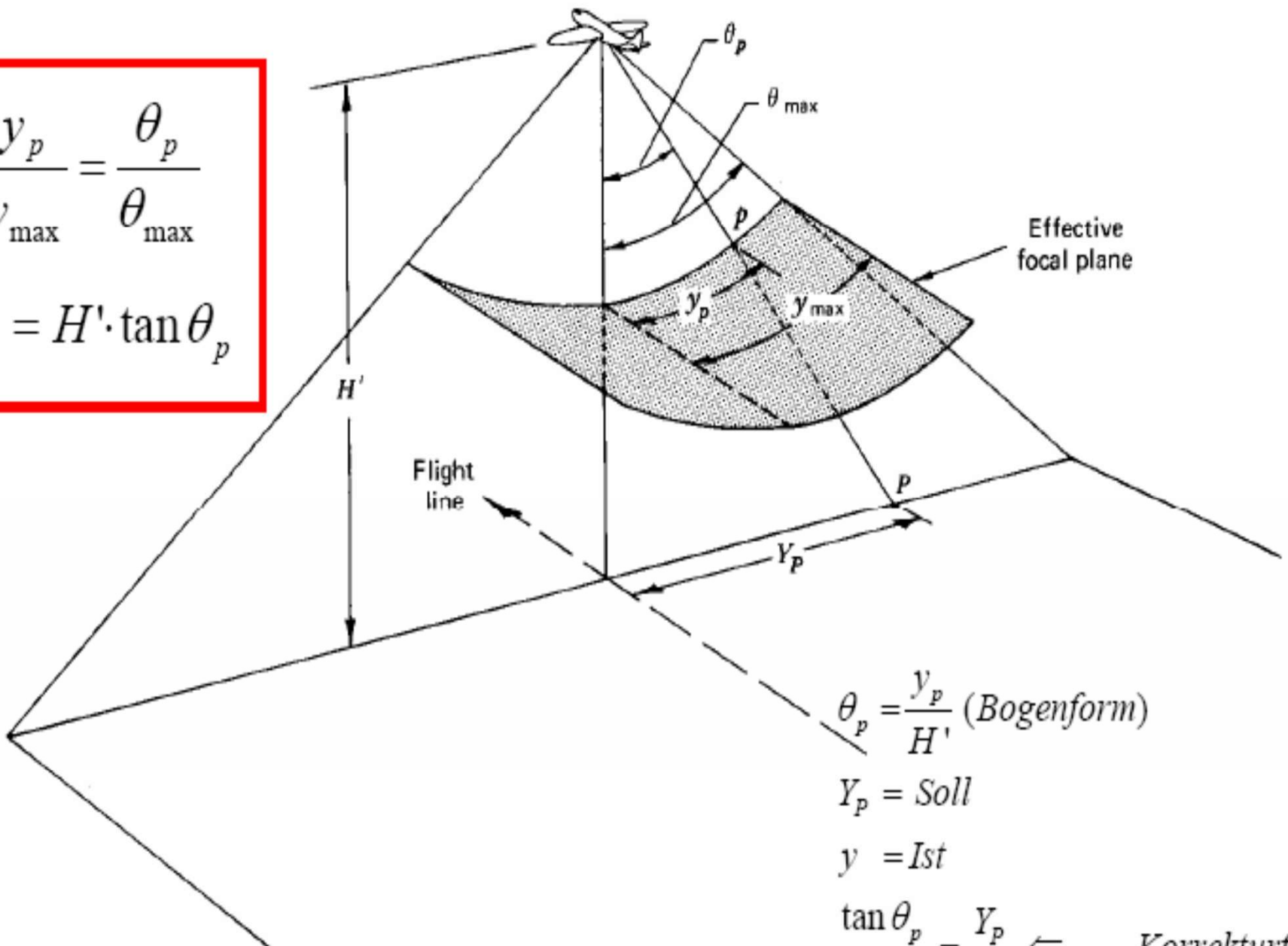


Instantaneous Field of View (IFOV) = $\Delta\theta = \omega$



$$\frac{y_p}{y_{\max}} = \frac{\theta_p}{\theta_{\max}}$$

$$Y_p = H' \cdot \tan \theta_p$$



$$\theta_p = \frac{y_p}{H'} \text{ (Bogenform)}$$

$Y_p = \text{Soll}$

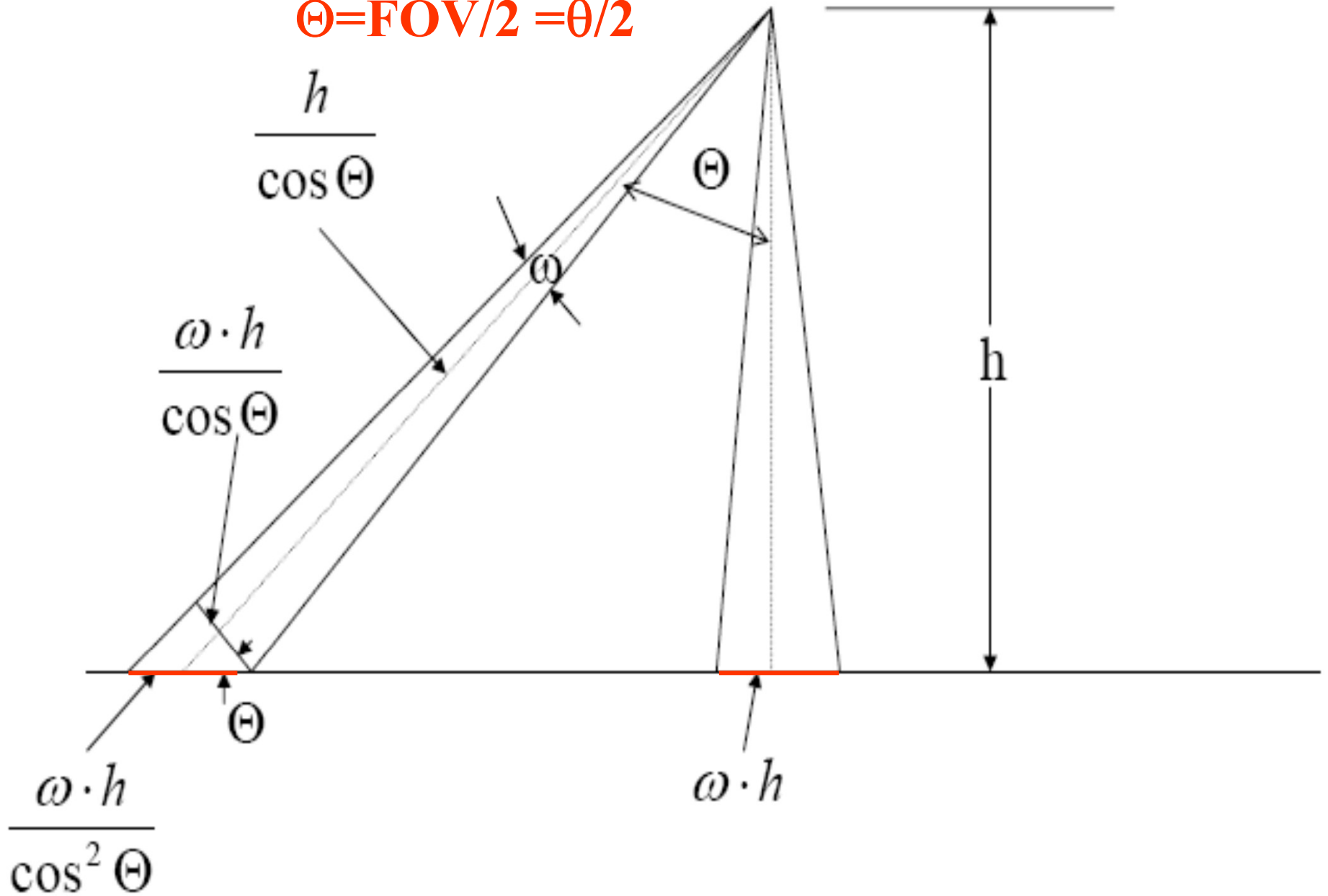
$y = \text{Ist}$

$$\frac{\tan \theta_p}{\theta_p} = \frac{Y_p}{y} \leftarrow \text{Korrekturform}$$

Panoramakorrektur

$$\text{IFOV} = \Delta\theta = \omega$$

$$\Theta = \text{FOV}/2 = \theta/2$$



Quickbird 70 cm pan (left) versus *Ikonos* 1m pan (right)



Tennis Centre, Melbourne

Comparison between IKONOS and Quickbird

◆ Item	IKONOS	Quickbird
◆ Focal Length	10m	9m
◆ Altitude	680km	450km
◆ No of pixel/l	13,800	27,500
◆ FOV	0.93deg.	2.1deg.
◆ Resolution	0.82m	0.61m
◆ Coverage	11x11km	16.5x16.5km
•IFOV	1.206 μ rad.	1.356 μ rad.

*Example

1. ถ้าต้องการถ่ายภาพให้ได้ความชัดถึง 10 cm (nadir). จะต้องให้ดาวเทียม quick bird ถ่ายภาพที่ระดับความสูงเท่าใด

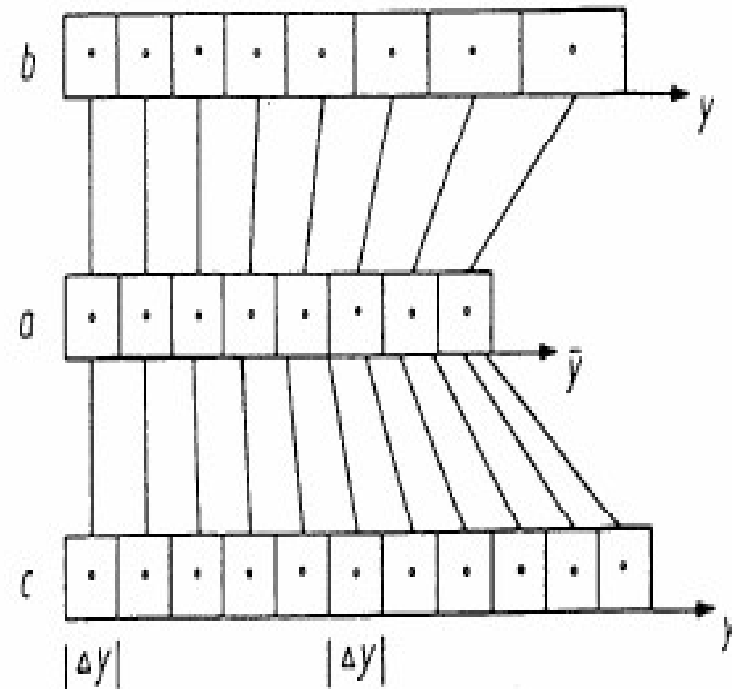
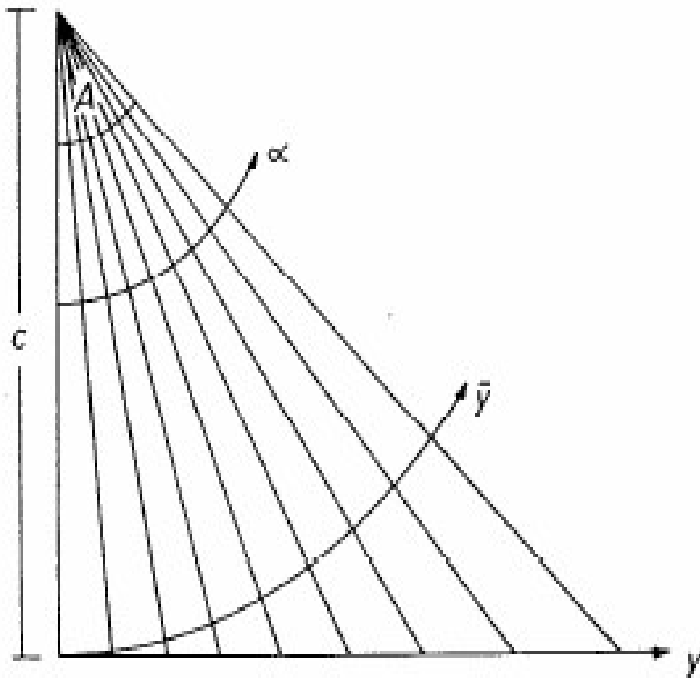
ถ้าปัจจุบัน sensor altitude = 450 km. Res.=0.60 m

2. ดาวเทียมดวงหนึ่งถ่ายได้ละเอียดที่ 80 cm (nadir). sensor อยู่สูงเท่าใดและบริเวณไกลสุด off nadir จะถ่ายภาพของวัตถุได้อย่างชัดที่สุดเมื่อวัตถุมีขนาดเท่าใด ถ้าปัจจุบัน IFOV=1.0

$\mu\text{rad. FOV} = 90^\circ$

$$\text{Ans. } h = 0.8 / 1 \times 10^{-6} = 800,000 \text{ m.} = 800 \text{ km}$$

$$\text{Res}' = 0.8 / \cos^2(90/2) = 1.6 \text{ m.}$$

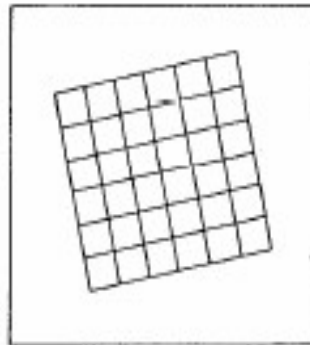
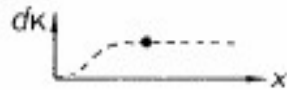


Panoramaverzerrung

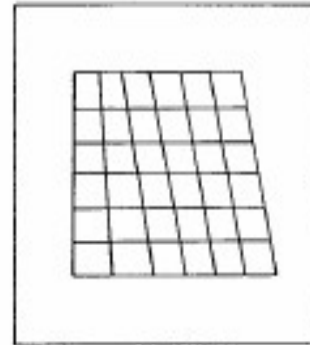
- a) Originaldaten einer Halbzeile
- b) panoramakorrigierte Daten mit Bildelementen ungleicher Größe
- c) panoramakorrigierte Daten mit Bildelementen gleicher Größe (interpoliert)

Parametrische Entzerrung (Forts.)

c) Kantung dx

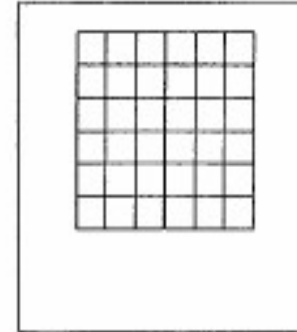
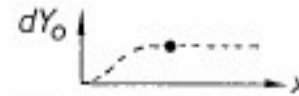


Photographie

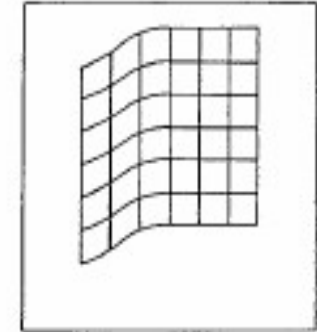
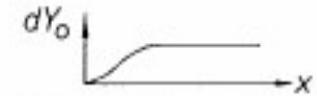


Abtaster

e) Kursabweichung dY_0

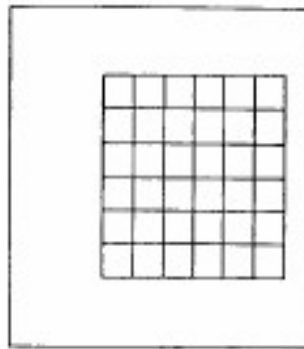


Photographie

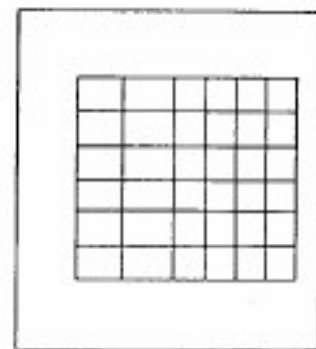
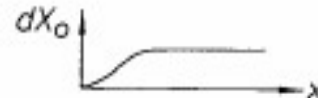


Abtaster

1) Translation dX_0 (Fluggeschwindigkeit)

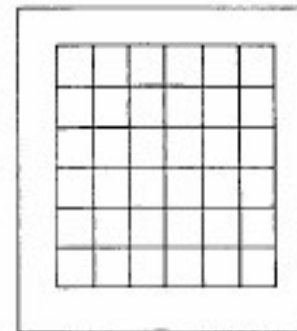
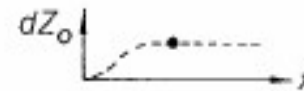


Photographie

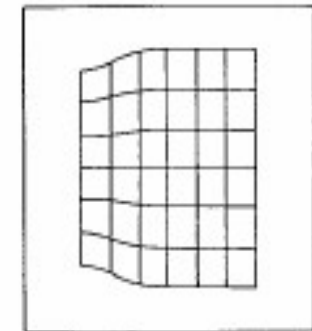
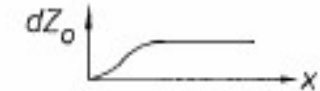


Abtaster

f) Flughthenänderung dZ_0

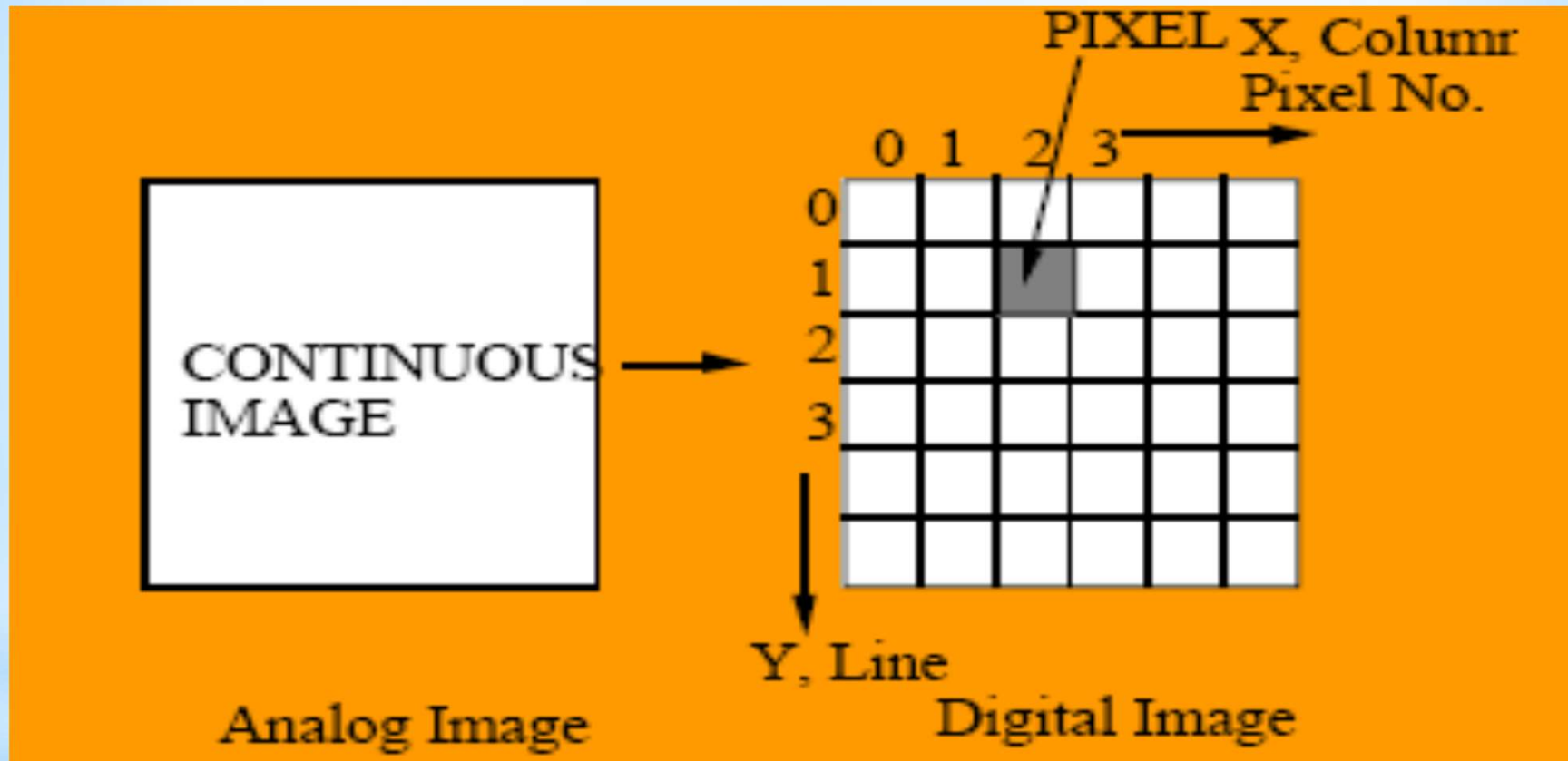


Photographie



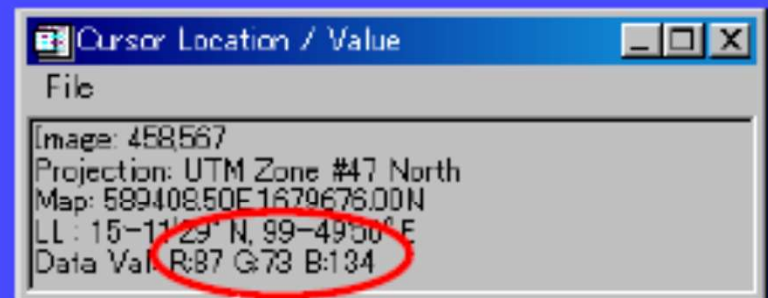
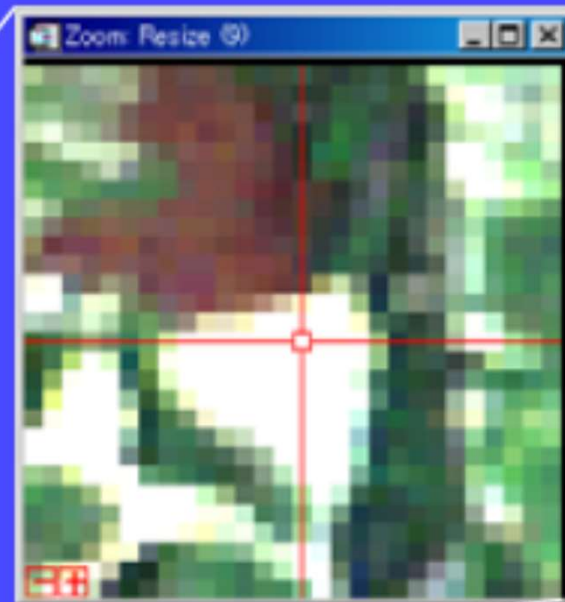
Abtaster

* Digital Image Data Pixel



Pixel (Picture Element), pixel has a value $f(x,y)$
 x,y :integer, f : brightness in most case, integer

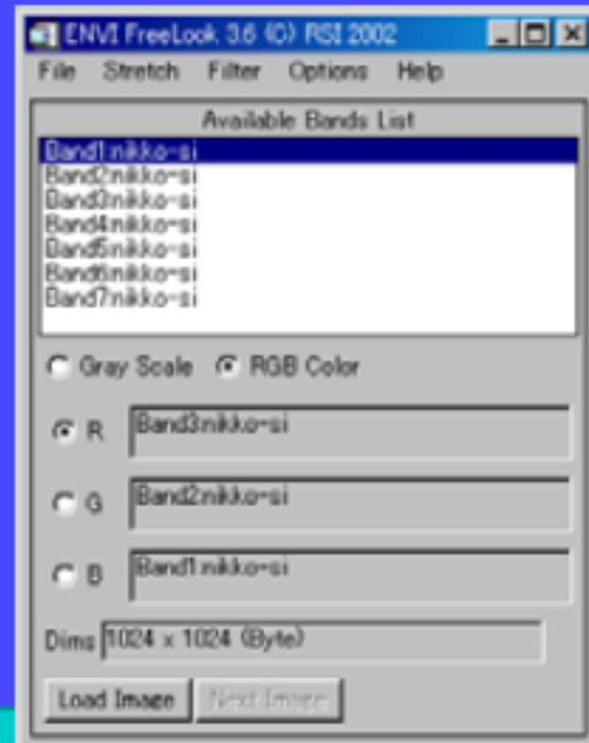
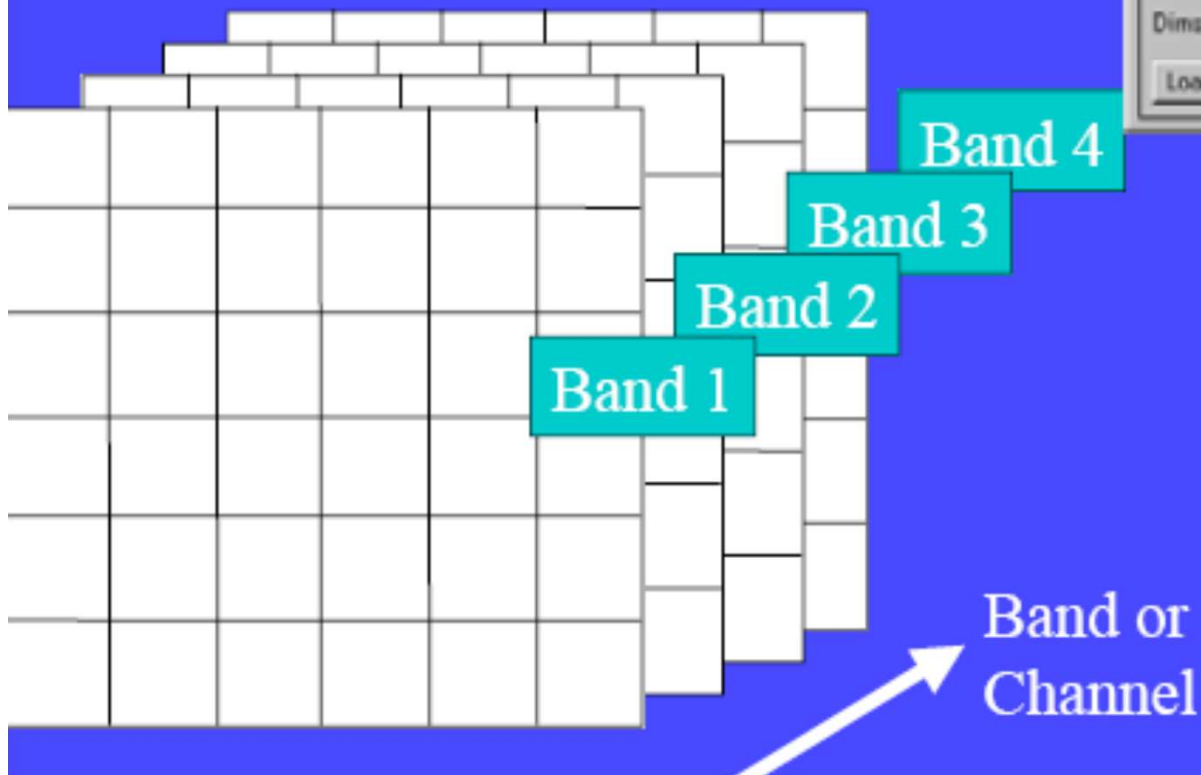
Pixel II



Pixel Value

Multi Channel Image

Color Image: 3 channel for R,G,B
Landsat TM 7 Channel



*Bit and Binary System

- The gray level of each pixel is recorded and stored as finite number of bits
- If there are k bits/pixel, total of 2^k gray levels over the range 0 to 2^k-1
- Example of 3 bits image

Bit2	Bit1	Bit0	Gray level	Bit2	Bit1	Bit0	Gray level
0	0	0	0	1	0	0	4
0	0	1	1	1	0	x	5
0	1	0	2	1	0	0	x
0	1	1	x	1	1	x	7

If $k = 8$, the group of bits is called “byte”.

* Binary system in computer memory

Pixel value is stored in limited space in a computer memory, 1 unit = 1 byte = 8 bits

8 bits has $2^8 = 2 \times 2 \times 2 \times 2 \times 2 \times 2 \times 2 \times 2 = 256$

Combinations of on/off at bits.

Thus k bits unsigned integer has 0 to $2^k - 1$ of data range.

8 bits(1 byte)/ pixel 0 to 255

16 bits(2 bytes)/pixel 0 to 65535

1024 bytes = 1kB

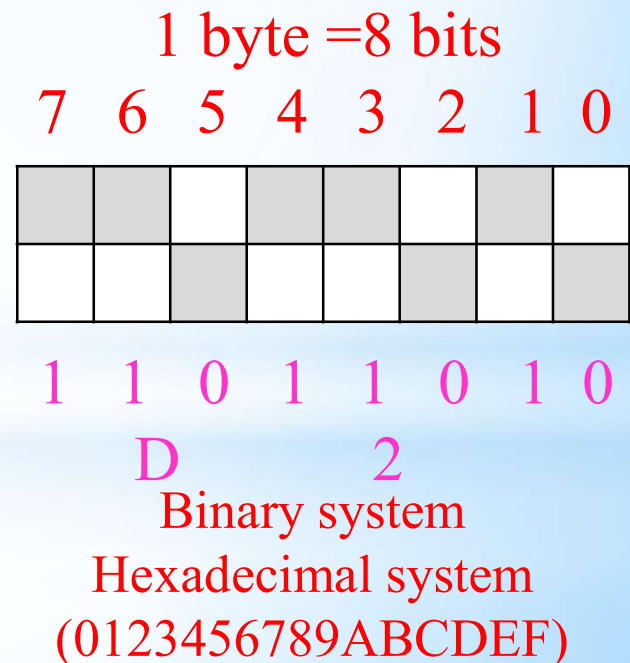
1024 kB = 1MB

1024 MB = 1GB

1024 GB = 1TB

Image size in Bytes

1024 width x 1024 height x 7 bands/³³1 byte/pixel => 7 MB



*Reference:

Assoc.Prof.Dr.HONDA Kiyoshi, Lecture Note .School of Engineering and Technology ,AIT Thailand.

Suggested Web Sites:

- *Fundamentals of Remote Sensing, Canada Centre for Remote Sensing, Canada*
- AUSLIG (<http://www.auslig.gov.au/>)
- Space Imaging (<http://www.spaceimage.com/>)
- Australian Bureau of Meteorology
(<http://www.bom.gov.au/sat/intro/paper1intro.shtml>)
- JPL Radar Site (<http://www.jpl.nasa.gov/radar/sircxsar/>)
- Australian geological Survey Organization (<http://www.agso.gov.au/>)

Thank you for your kind attention

